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## MAX14827

## IO-Link Device Transceiver

### General Description

The MAX14827 integrates the high-voltage functions commonly found in industrial sensors, including drivers and regulators. The MAX14827 features two ultra low-power drivers with active reverse-polarity protection. Operation is specified for normal 24V supply voltages up to 60V. Transient protection is simplified due to high voltage tolerance allowing the use of micro TVS.

The device features a flexible control interface. Pin-control logic inputs allow for operation with switching sensors that do not use a microcontroller. For sensors that use a microcontroller, an SPI interface is available with extensive diagnostics. For IO-Link operation, a three-wire UART interface is provided, allowing interfacing to the microcontroller UART. Finally, a multiplexed UART/SPI option allows using one serial microcontroller interface for shared SPI and UART interfaces.

The device includes on-board 3.3V and 5V linear regulators for low-noise analog/logic supply rails.

The MAX14827 is available in a (4mm x 4mm) 24-pin TQFN package and a (2.5mm x 2.5mm) 25-pin wafer-level package (WLP) and is specified over the extended -40°C to +125°C temperature range.

### Applications

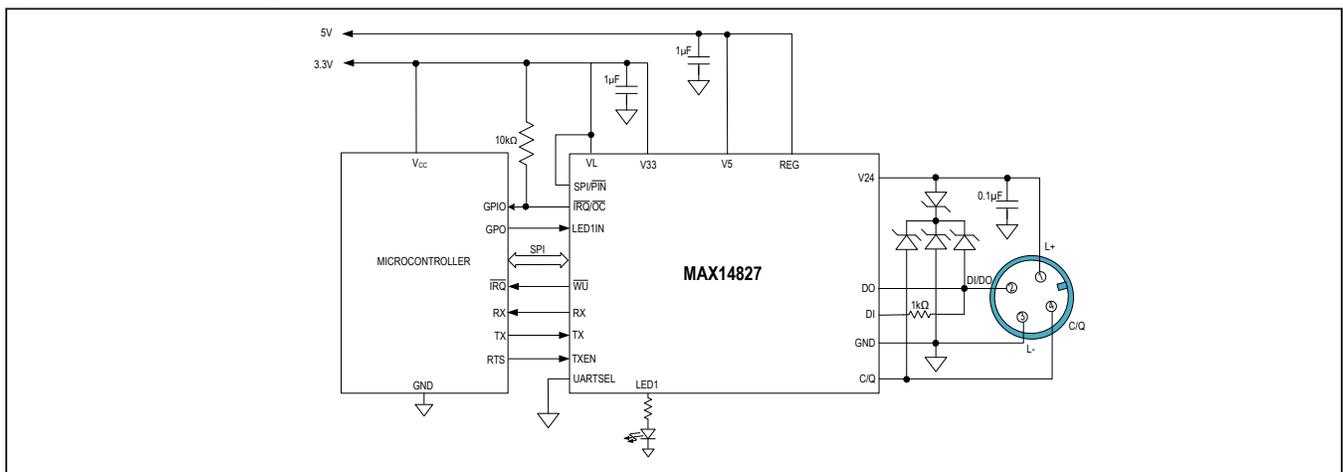
- Industrial sensors
- IO-Link sensors and actuators
- Safety applications

### Benefits and Features

- High Configurability and Integration Reduce SKUs
  - IO-Link Compliant Transceiver
  - Auxiliary 24V Digital Output and Input
  - 2.3Ω (typ) Driver On-Resistance
  - Selectable Driver Current: 50mA to 250mA
  - SPI or Pin-Control Interface for Configuration and Monitoring
  - Multiplexed SPI/UART Interface Option
  - 5V and 3.3V Linear Regulators
  - Optional External Transistor Supports Higher Regulator Load Capability
  - Integrated LED Driver
- Integrated Protection Enables Robust Communication
  - 65V Absolute Maximum Ratings on Interface and Supply Pins Allows for Flexible TVS Protection
  - 9V to 60V Specified Operation
  - Glitch Filters for Improved Burst Resilience and Noise
  - Selectable Over-Current Auto-Retry Timing
  - Thermal Shutdown Auto-Retry Cycling
  - Hot-Plug Supply Protection up to 36V
  - Reverse Polarity Protection of All Sensor Interface Inputs/Outputs
  - -40°C to +125°C Operating Temperature Range

**Ordering Information** appears at end of data sheet.

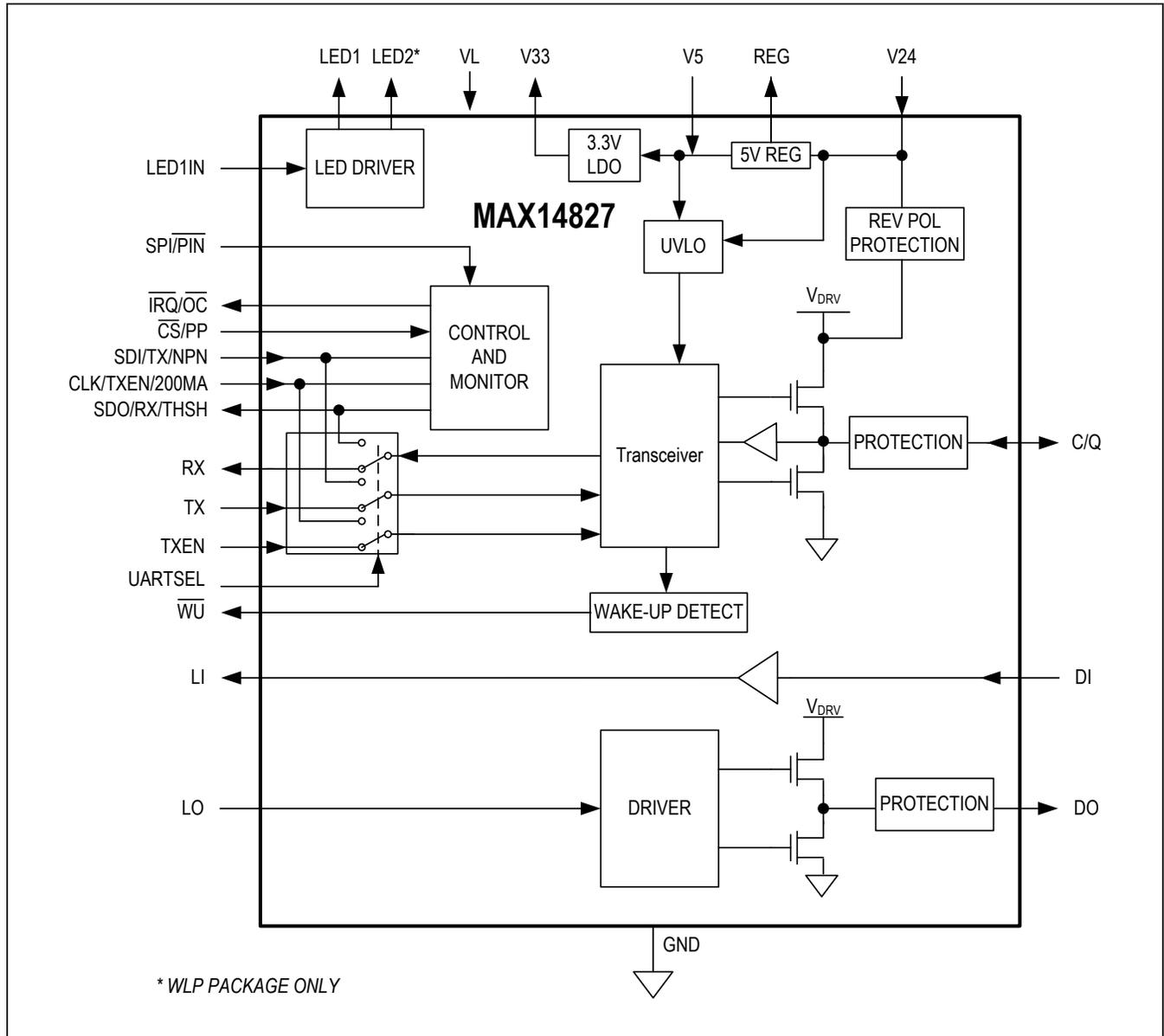
### Typical Operating Circuit



IO-Link is a registered trademark of Profibus User Organization (PNO).

SPI is a trademark of Motorola, Inc.

Functional Diagram



### Absolute Maximum Ratings

(All voltages referenced to GND, unless otherwise noted.)

V24	-70V to +65V
REG	-0.3V to (V <sub>5</sub> + 16V)
V5, VL	-0.3V to +6V
V33	-0.3V to (V <sub>5</sub> + 0.3V)
C/Q, DO, DI	MIN: Larger of -70V and (V <sub>24</sub> - 70V) to MAX: the lower of +70V and (V <sub>24</sub> + 70V)

Logic Inputs:

CS/PP, TXEN, TX, LED1IN, LI, UARTSEL, CLK/TXEN/200MA, SPI/PIN, SDI/TX/NPN	-0.3V to (V <sub>L</sub> + 0.3V)
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Logic Outputs:

RX, LI, LO WU, SDO/RX/THSH	-0.3V to (V <sub>L</sub> + 0.3V)
IRQ/OC	-0.3V to +6V
LED1, LED2	-0.3V to (V <sub>5</sub> +0.3V)

Continuous Current Into GND and V24	±1A
Continuous Current Into C/Q and DO	±500mA
Continuous Current Into V5 and REG	±100mA
Continuous Current Into Any Other Pin	±50mA
Continuous Power Dissipation	
TQFN (derate 27.8mW/°C above +70°C)	2222mW
WLP (derate 22.7mW/°C above +70°C)	1816mW
Operating Temperature Range	-40°C to +125°C
Maximum Junction Temperature	Internally Limited
Storage Temperature Range	-65°C to +150°C
Soldering Temperature (reflow, TQFN and WLP)	+260°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

### Package Information

<b>PACKAGE TYPE: 24 TQFN</b>	
Package Code	T2444+4
Outline Number	<a href="#">21-0139</a>
Land Pattern Number	<a href="#">90-0022</a>
<b>THERMAL RESISTANCE, FOUR-LAYER BOARD</b>	
Junction to Ambient (θ <sub>JA</sub> )	36°C/W
Junction to Case (θ <sub>JC</sub> )	3°C/W

<b>PACKAGE TYPE: 25 WLP</b>	
Package Code	W252L2+1
Outline Number	<a href="#">21-0787</a>
Land Pattern Number	Refer to <a href="#">Application Note 1891</a>
<b>THERMAL RESISTANCE, FOUR-LAYER BOARD</b>	
Junction to Ambient (θ <sub>JA</sub> )	71°C/W

For the latest package outline information and land patterns (footprints), go to [www.maximintegrated.com/packages](http://www.maximintegrated.com/packages). Note that a "+", "#", or "-" in the package code indicates RoHS status only. Package drawings may show a different suffix character, but the drawing pertains to the package regardless of RoHS status.

Package thermal resistances were obtained using the method described in JEDEC specification JESD51-7, using a four-layer board. For detailed information on package thermal considerations, refer to [www.maximintegrated.com/thermal-tutorial](http://www.maximintegrated.com/thermal-tutorial).

**DC Electrical Characteristics**

(V<sub>24</sub> = 9V to 60V, V<sub>5</sub> = 4.5V to 5.5V, V<sub>L</sub> = 2.5V to 5.5V, V<sub>GND</sub> = 0V; REG unconnected, all logic inputs at V<sub>L</sub> or GND; T<sub>A</sub> = -40°C to +125°C, unless otherwise noted. Typical values are at V<sub>24</sub> = 24V, V<sub>5</sub> = 5V, V<sub>L</sub> = 3.3V, and T<sub>A</sub> = +25°C, unless otherwise noted.) (Note 1)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
V <sub>24</sub> Supply Voltage	V <sub>24</sub>			9		60	V
V <sub>24</sub> Undervoltage-Lockout Threshold	V <sub>24UVLO</sub>	V <sub>24</sub> rising		6	7.8	9	V
		V <sub>24</sub> falling		6	7.2	9	
V <sub>24</sub> Undervoltage-Lockout-Threshold Hysteresis	V <sub>24UVLO_HYST</sub>				570		mV
V <sub>24</sub> Supply Current	I <sub>24</sub>	V <sub>5</sub> powered externally, REG is unconnected	C/Q and DO disabled (CQ_Dis = 1, DO_Dis = 1)		0.14	0.5	mA
			C/Q and DO in push-pull configuration, CL[10] = 11, C/Q and DO high, no load on C/Q or DO		1.1	1.75	
			C/Q and DO in push-pull configuration, CL[10] = 11, C/Q and DO low, no load on C/Q or DO		1.4	1.8	
V <sub>24</sub> Low-Voltage Warning Threshold	V <sub>24W</sub>			14.5	16.5	18	V
V <sub>5</sub> Supply Voltage				4.5		5.5	V
V <sub>5</sub> Undervoltage-Lockout Threshold	V <sub>5UVLO</sub>	V <sub>5</sub> rising		2.8	3.5	4.5	V
		V <sub>5</sub> falling		2.8	3.45	4.5	
V <sub>5</sub> Supply Current	I <sub>5_IN</sub>	External 5V applied to V <sub>5</sub> , REG is unconnected, no load on LED1 or LED2	C/Q and DO disabled (CQ_Dis = 1, DO_Dis = 1), V <sub>33</sub> disabled (V <sub>33_Dis</sub> = 1)		0.64	0.9	mA
			C/Q and DO in push-pull configuration, CL[10] = 11, C/Q and DO high, V <sub>33</sub> enabled, no load on C/Q, DO, or V <sub>33</sub>		1.37	1.75	
			C/Q and DO in push-pull configuration, CL[10] = 11, C/Q and DO low, V <sub>33</sub> enabled, no load on C/Q, DO, or V <sub>33</sub>		1.41	1.8	

## DC Electrical Characteristics (continued)

( $V_{24} = 9V$  to  $60V$ ,  $V_5 = 4.5V$  to  $5.5V$ ,  $V_L = 2.5V$  to  $5.5V$ ,  $V_{GND} = 0V$ ; REG unconnected, all logic inputs at  $V_L$  or GND;  $T_A = -40^\circ C$  to  $+125^\circ C$ , unless otherwise noted. Typical values are at  $V_{24} = 24V$ ,  $V_5 = 5V$ ,  $V_L = 3.3V$ , and  $T_A = +25^\circ C$ , unless otherwise noted.) (Note 1)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
VL Logic-Level Supply Voltage	$V_L$		2.5		5.5	V	
VL Undervoltage Threshold	$V_{LUVLO}$		0.9	1.7	2.4	V	
VL Logic-Level Supply Current	$I_L$	All logic inputs at $V_L$ or GND, all logic outputs unconnected		0.25	3	$\mu A$	
<b>5V LINEAR REGULATOR/CONTROLLER (V5)</b>							
V5 Output Voltage	$V_5$	REG = V5, no load on V5, $9V \leq V_{24} \leq 60V$	4.75	5.00	5.25	V	
Load Regulation	$\Delta V_{5\_LDR}$	REG = V5, $0mA < I_{LOAD} < 30mA$ , $V_{24} = 24V$		0.02	0.2	%	
Line Regulation	$\Delta V_{5\_LNR}$	REG = V5, $I_{LOAD} = 1mA$ , $V_{24}$ from 9V to 60V		0.01	4	mV/V	
REG Output Current	$I_{REG}$	Internal regulator or external NPN			30	mA	
V24 REG Dropout Voltage	$\Delta V_{REG}$	$V_{24} = 9V$ , $V_5 = 4.5V$ , $I_{REG} = 5mA$		2.35		V	
REG Open Voltage	$V_{REG\_OPN}$	$V_{24} = 60V$ , $V_5 = 4.5V$ , no load on REG	10	13	16	V	
V5 Capacitance	$CV_5$	Allowed capacitance on V5, REG connected to V5 (Note 2)	0.8	1	2	$\mu F$	
<b>3.3V LINEAR REGULATOR (V33)</b>							
V33 Output Voltage	$V_{33}$	No load on V33	3.1	3.3	3.5	V	
V33 Load Regulation	$V_{33\_LDR}$	$0mA < I_{LOAD} < 30mA$	0	0.4	0.8	%	
V33 Capacitance	$CV_{33}$	Allowed capacitance on V33, V33 enabled (Note 3)	0.8	1		$\mu F$	
<b>C/Q, DO DRIVER</b>							
Driver On-Resistance	$R_{OH}$	High-side enabled, $V_{24} = 24V$ , $CL[10] = 11$ , $I_{LOAD} = -200mA$		2.65	4.6	$\Omega$	
	$R_{OL}$	Low-side enabled, $V_{24} = 24V$ , $CL[10] = 11$ , $I_{LOAD} = +200mA$		2.3	4.45		
Driver Current Limit	$I_{CL}$	SPI/ $\overline{PIN}$ = high, $V_{DRIVER} = (V_{24} - 3V)$ or $3V$ , $CL\_Dis = 0$	$CL[10] = 00$	50	65	80	mA
			$CL[10] = 01$	100	120	150	
			$CL[10] = 10$	200	230	275	
			$CL[10] = 11$	250	290	350	
		SPI/ $\overline{PIN}$ = low, $V_{DRIVER} = (V_{24} - 3V)$ or $3V$	CLK/TXEN/200MA = low	100	120	150	
			CLK/TXEN/200MA = high	200	230	275	
Driver Peak Current	$I_{CL\_PEAK}$	DC current			490	mA	
C/Q Leakage Current	$I_{LEAK\_CQ}$	C/Q driver is disabled ( $C/Q\_Dis = 1$ ), RX disabled ( $Rx\_Dis = 1$ ), $V_{24} = 24V$ , $(V_{24} - 65V) \leq V_{C/Q} \leq +60V$	-70		+10	$\mu A$	
DO Leakage Current	$I_{LEAK\_DO}$	DO driver is disabled ( $DO\_Dis = 1$ ), $V_{24} = 24V$ , $(V_{24} - 65V) \leq V_{DO} \leq +60V$	-10		+10	$\mu A$	
C/Q Output Reverse Current	$I_{REV\_CQ}$	C/Q driver enabled and in push-pull configuration, $V_{24} = 30V$ , $V_{C/Q} = (V_{24} + 5V)$ or $(V_{GND} - 5V)$	-60		+1000	$\mu A$	

### DC Electrical Characteristics (continued)

( $V_{24} = 9V$  to  $60V$ ,  $V_5 = 4.5V$  to  $5.5V$ ,  $V_L = 2.5V$  to  $5.5V$ ,  $V_{GND} = 0V$ ; REG unconnected, all logic inputs at  $V_L$  or GND;  $T_A = -40^\circ C$  to  $+125^\circ C$ , unless otherwise noted. Typical values are at  $V_{24} = 24V$ ,  $V_5 = 5V$ ,  $V_L = 3.3V$ , and  $T_A = +25^\circ C$ , unless otherwise noted.) (Note 1)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
DO Output Reverse Current	$I_{REV\_DO}$	DO driver enabled and in push-pull configuration, $V_{24} = 30V$ , $V_{DO} = (V_{24} + 5V)$ or $(V_{GND} - 5V)$		-60		+1000	$\mu A$
Weak Pulldown Current	$I_{PD}$	SPI/ $\overline{PIN}$ = high, driver disabled (CQ_Dis = 1, DO_Dis = 1)	$V_{DRIVER} = 5V$ , CQ_WPD = 1, DO_WPD = 1, CQ_WPU = 0, DO_WPU = 0	200	300	400	$\mu A$
			$V_{DRIVER} = 24V$ , CQ_WPD = 1, DO_WPD = 1, CQ_WPU = 0, DO_WPU = 0	200	470	1000	
Weak Pullup Current	$I_{PU}$	SPI/ $\overline{PIN}$ = high, driver disabled (CQ_Dis = 1, DO_Dis = 1), $V_{DRIVER} = V_{24} - 5V$	CQ_WPU = 1, DO_WPU = 1, CQ_WPD = 0, DO_WPD = 0,	-400	-300	-200	$\mu A$
<b>C/Q, DI RECEIVER</b>							
Input Voltage Range	$V_{IN}$	For valid RX/LI logic		$V_{24} - 65$		+65	V
C/Q, DI Input Threshold High	$V_{TH}$	C/Q driver disabled	$V_{24} > 18V$	11	11.8	12.5	V
			$V_{24} < 18V$	59	65.5	72	% of $V_{24}$
C/Q, DI Input Threshold Low	$V_{TL}$	C/Q driver disabled	$V_{24} > 18V$	9	9.8	10.5	V
			$V_{24} < 18V$	45	54.5	63	% of $V_{24}$
C/Q, DI Input Hysteresis	$V_{HYS\_CQ}$	C/Q driver disabled	$V_{24} > 18V$	2		V	
			$V_{24} < 18V$	11		% of $V_{24}$	
C/Q Input Capacitance	$C_{IN\_CQ}$	Driver disabled, weak pull-up and pull-down disabled, $f = 100kHz$		50		pF	
DI Input Capacitance	$C_{IN\_DI}$	$f = 100kHz$		10		pF	
C/Q Input Current	$I_{IN\_CQ}$	C/Q driver disabled (CQ_Dis = 1), C/Q receiver enabled, $V_{24} = 24V$	$-5V \leq V_{C/Q} \leq (V_{24} + 5V)$	-10		+30	$\mu A$
			$(V_{24} - 65V) \leq V_{C/Q} \leq +60V$	-70		+70	
DI Leakage Current	$I_{LEAK\_DI}$	DI receiver disabled (DI_Dis = 1), $V_{24} = 24V$ , $(V_{24} - 65V) \leq V_{DI} \leq +60V$		-40		+150	$\mu A$
DI Input Current	$I_{IN\_DI}$	DI receiver enabled, $V_{24} = 24V$	$-5V \leq V_{DI} \leq (V_{24} + 5V)$	-10		+35	$\mu A$
			$(V_{24} - 65V) \leq V_{DI} \leq +60V$	-40		+200	

**DC Electrical Characteristics (continued)**

( $V_{24} = 9V$  to  $60V$ ,  $V_5 = 4.5V$  to  $5.5V$ ,  $V_L = 2.5V$  to  $5.5V$ ,  $V_{GND} = 0V$ ; REG unconnected, all logic inputs at  $V_L$  or GND;  $T_A = -40^\circ C$  to  $+125^\circ C$ , unless otherwise noted. Typical values are at  $V_{24} = 24V$ ,  $V_5 = 5V$ ,  $V_L = 3.3V$ , and  $T_A = +25^\circ C$ , unless otherwise noted.) (Note 1)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
<b>LOGIC INPUTS (<math>\overline{CS}/PP</math>, TXEN, TX, LO, LED1IN, CLK/TXEN/200MA, SPI/<math>\overline{PIN}</math>, SDI/TX/NPN)</b>						
Logic Input Voltage Low	$V_{IL}$				$0.2 \times V_L$	V
Logic Input Voltage High	$V_{IH}$		$0.8 \times V_L$			V
Logic Input Leakage Current	$I_{LEAK}$	Logic input = GND or $V_L$	-1		+1	$\mu A$
<b>LOGIC OUTPUTS (RX, LI, <math>\overline{WU}</math>, <math>\overline{IRQ}/\overline{OC}</math>, SDO/RX/THSH)</b>						
Logic Output Voltage Low	$V_{OL}$	$I_{OUT} = -5mA$			0.4	V
Logic Output Voltage High	$V_{OH}$	$I_{OUT} = 5mA$	$V_5 - 0.4$			V
$\overline{IRQ}/\overline{OC}$ Open-Drain Leakage Current	$I_{LK\_OD}$	$\overline{IRQ}/\overline{OC}$ high impedance, $\overline{IRQ}/\overline{OC} = GND$ or $V_L$	-1		+1	$\mu A$
SDO Leakage Current	$I_{LK\_SDO}$	SPI/ $\overline{PIN}$ = high, $\overline{CS}/PP$ = high, SDO/RX/THSH = GND or $V_L$	-1		+1	$\mu A$
RX, LI Leakage Current	$I_{LK\_RXLI}$	SPI/ $\overline{PIN}$ = high, DI_Dis = 1, RX_Dis = 1, RX/LI = GND or $V_L$	-1		+1	$\mu A$
<b>LED DRIVERS (LED1, LED2)</b>						
LED Output Voltage Low	$V_{LEDOL}$	$I_{OUT} = -5mA$			0.4	V
LED Output Voltage High	$V_{LEDOH}$	$I_{OUT} = 10mA$	$V_5 - 0.4$			V
<b>THERMAL MANAGEMENT</b>						
Thermal Warning Threshold	$T_{WRN}$	Die junction temperature rising, TempW and TempWInt bits are set		+140		$^\circ C$
Thermal Warning Threshold Hysteresis	$T_{WRN\_HYS}$	Die junction temperature falling, TempW bit cleared		15		$^\circ C$
Per-Driver Thermal Shutdown Temperature	$T_{SHUT\_D}$	Driver temperature rising, temperature at which the driver is turned off		+160		$^\circ C$
Per-Driver Thermal Shutdown Temperature Hysteresis	$T_{SHUT\_DHYS}$	Driver temperature falling		15		$^\circ C$
IC Thermal Shutdown	$T_{SHUT\_IC}$	Die temperature rising, ThShut and ThuShutInt bits are set		+170		$^\circ C$
IC Thermal-Shutdown Hysteresis	$T_{SHUT\_ICHYS}$	Die temperature falling, ThShut bit is cleared		15		$^\circ C$

## AC Electrical Characteristics

( $V_{24} = 18V$  to  $30V$ ,  $V_5 = 4.5V$  to  $5.5V$ ,  $V_L = 2.5V$  to  $5.5V$ ,  $V_{GND} = 0V$ ; REG unconnected, all logic inputs at  $V_L$  or GND;  $T_A = -40^\circ C$  to  $+125^\circ C$ , unless otherwise noted. Typical values are at  $V_{24} = 24V$ ,  $V_5 = 5V$ ,  $V_L = 3.3V$ , and  $T_A = +25^\circ C$ , unless otherwise noted.) (Note 2)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
<b>C/Q, DO DRIVER</b>						
Driver Low-to-High Propagation Delay	$t_{PDLH\_PP}$	Push-pull and PNP configuration, Figure 1		0.16	0.4	$\mu s$
Driver High-to-Low Propagation Delay	$t_{PDHL\_PP}$	Push-pull and NPN configuration, Figure 1		0.28	0.4	$\mu s$
Driver Skew	$t_{SKEW}$	Push-pull configuration, Figure 1 $ t_{PDLH} - t_{PDHL} $	-0.3		+0.3	$\mu s$
Driver Rise Time	$t_{RISE}$	Push-pull and PNP configuration, Figure 1		0.12	0.4	$\mu s$
Driver Fall Time	$t_{FALL}$	Push-pull and NPN configuration, Figure 1		0.12	0.4	$\mu s$
Driver Enable Time High	$t_{ENH}$	Push-pull and PNP configuration, CQDOPar = 1 for DO, Figure 2		0.15	0.4	$\mu s$
Driver Enable Time Low	$t_{ENL}$	Push-pull and NPN configuration, CQDOPar = 1 for DO, Figure 3		0.27	0.4	$\mu s$
Driver Disable Time High	$t_{DISH}$	Push-pull and PNP configuration, CQDOPar = 1 for DO, Figure 2		1.8	3	$\mu s$
Driver Disable Time Low	$t_{DISL}$	Push-pull and NPN configuration, CQDOPar = 1 for DO, Figure 3		1.5	3	$\mu s$
<b>C/Q, DI RECEIVER (Figure 4)</b>						
C/Q Receiver Low-to-High Propagation Delay	$t_{PRLH\_CQ}$	SPI/ $\overline{PIN}$ = high or low, CQFil = 0	0.85	1.3	2.1	$\mu s$
		SPI/ $\overline{PIN}$ = high, CQFil = 1	0.2	0.3	0.5	
C/Q Receiver High-to-Low Propagation Delay	$t_{PRHL\_CQ}$	SPI/ $\overline{PIN}$ = high or low, CQFil = 0	0.85	1.3	2.1	$\mu s$
		SPI/ $\overline{PIN}$ = high, CQFil = 1	0.2	0.3	0.5	
DI Receiver Low-to-High Propagation Delay	$t_{PRLH\_DI}$		1.3	2.2	3.5	$\mu s$
DI Receiver High-to-Low Propagation Delay	$t_{PRHL\_DI}$		1.3	2.2	3.5	$\mu s$
<b>DRIVER CURRENT LIMITING</b>						
Blanking Time	$t_{CL\_ARBL}$	SPI/ $\overline{PIN}$ = high	CL_BL[10] = 00	0.128		ms
			CL_BL[10] = 01	0.5		
			CL_BL[10] = 10	1		
			CL_BL[10] = 11	5		
		SPI/ $\overline{PIN}$ = low	0.128			
Autoretry Period	$t_{CL\_ARP}$	SPI/ $\overline{PIN}$ = high, ArEn = 1 (Note 3)	TAr[10] = 00	50		ms
			TAr[10] = 01	100		
			TAr[10] = 10	200		
			TAr[10] = 11	500		

### AC Electrical Characteristics (continued)

( $V_{24} = 18V$  to  $30V$ ,  $V_5 = 4.5V$  to  $5.5V$ ,  $V_L = 2.5V$  to  $5.5V$ ,  $V_{GND} = 0V$ ; REG unconnected, all logic inputs at  $V_L$  or GND;  $T_A = -40^\circ C$  to  $+125^\circ C$ , unless otherwise noted. Typical values are at  $V_{24} = 24V$ ,  $V_5 = 5V$ ,  $V_L = 3.3V$ , and  $T_A = +25^\circ C$ , unless otherwise noted.) (Note 2)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
<b>WAKE-UP DETECTION (Figure 5)</b>						
Wake-Up Input Minimum Pulse Width	$t_{WUMIN}$	$C_L = 3nF$	55	66	75	$\mu s$
Wake-Up Input Maximum Pulse Width	$t_{WUMAX}$		85	95	110	$\mu s$
$\overline{WU}$ Output Low Time	$t_{WUL}$	Valid wake-up condition on C/Q	100	200	300	$\mu s$
<b>SPI TIMING (<math>\overline{CS}/PP</math>, CLK/TXEN/200MA, SDI, TX/NPN, SDO/RX/THSH) (Figure 6)</b>						
Maximum SPI Clock Frequency			12.5			MHz
CLK/TXEN/200MA Clock Period	$t_{CH+CL}$		80			ns
CLK/TXEN/200MA Pulse-Width High	$t_{CH}$		40			ns
CLK/TXEN/200MA Pulse-Width Low	$t_{CL}$		40			ns
$\overline{CS}/PP$ Fall to CLK/TXEN/200MA Rise Time	$t_{CSS}$		20			ns
CLK/TXEN/200MA Rise to $\overline{CS}/PP$ Rise Hold Time	$t_{CSH}$		40			ns
SDI/TX/NPN Hold Time	$t_{DH}$		10			ns
SDI/TX/NPN Setup Time	$t_{DS}$				25	ns
Output Data Propagation Delay	$t_{DO}$				20	ns
SDO/RX/THSH Rise and Fall Times	$t_{FT}$				20	ns
Minimum $\overline{CS}/PP$ Pulse	$t_{CSW}$				10	ns

**Note 1:** All devices are 100% production tested at  $T_A = +25^\circ C$ . Limits over the operating temperature range are guaranteed by design.

**Note 2:** Not production tested. Guaranteed by design.

**Note 3:** Autoretry functionality is not available in pin-mode.

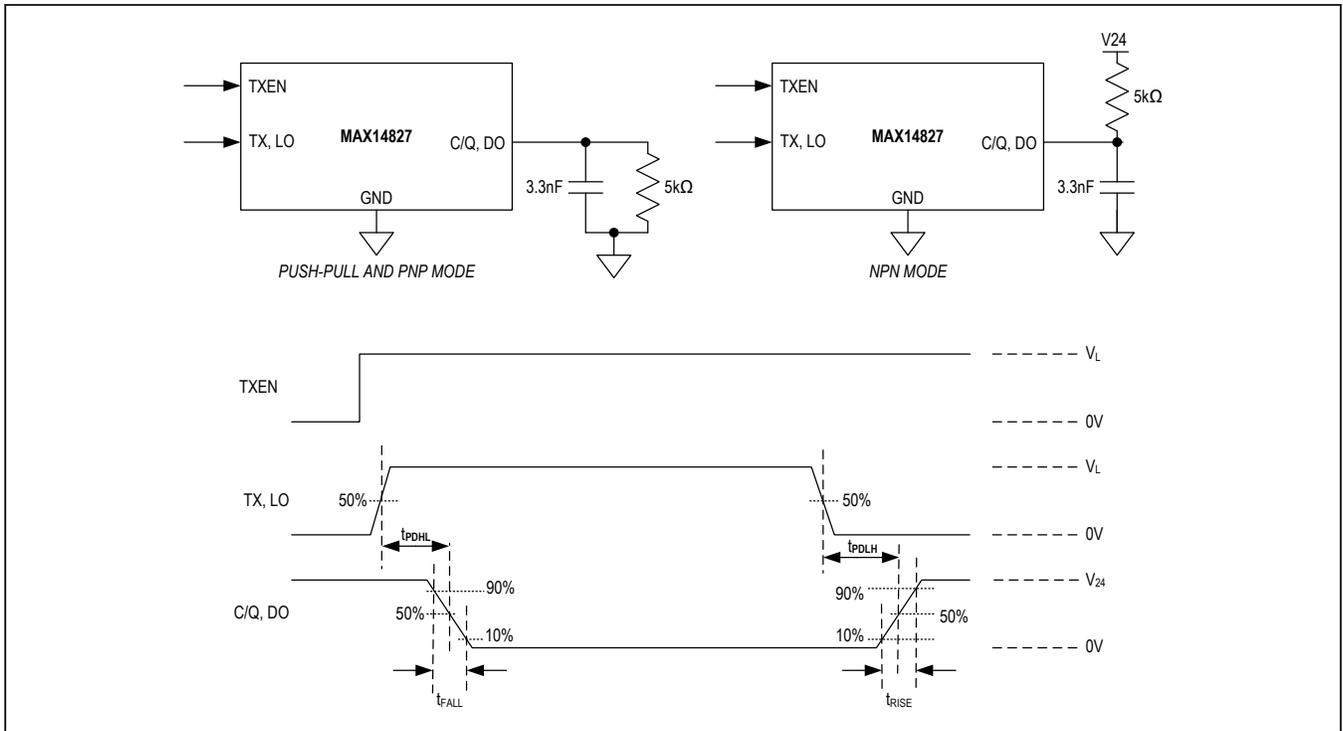


Figure 1. C/Q and LO Driver Propagation Delays and Rise/Fall Times

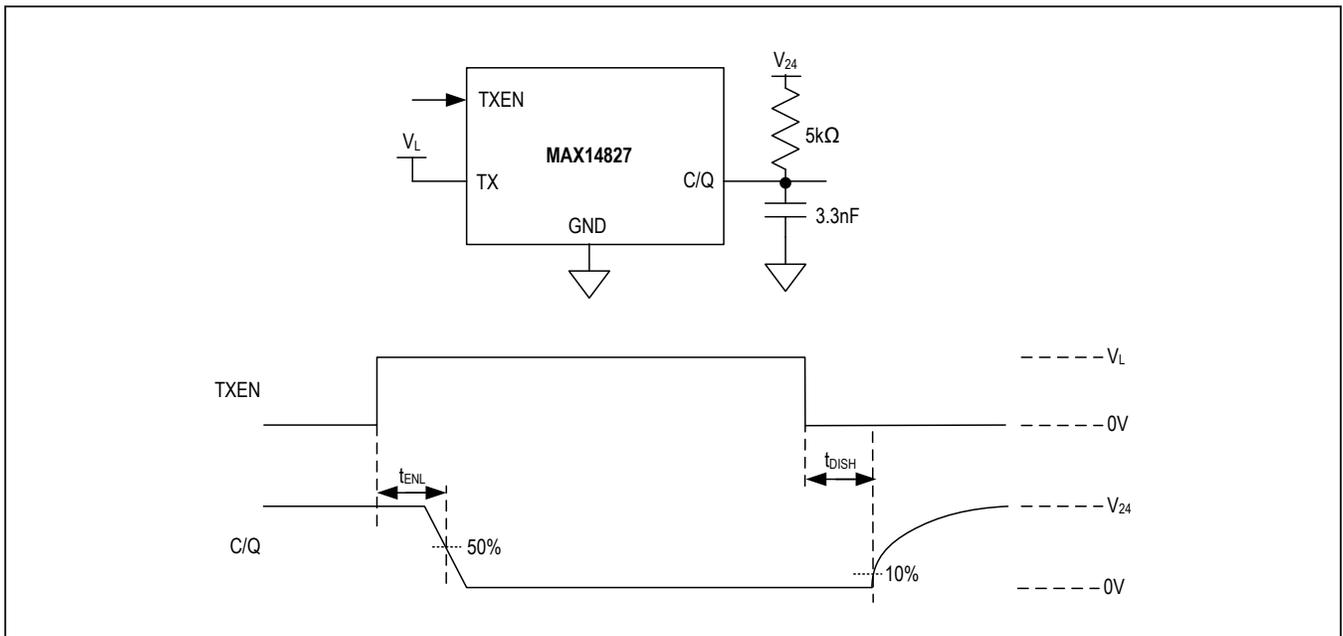


Figure 2. C/Q Driver Enable Low and Disable High Timing with External Pullup Resistor

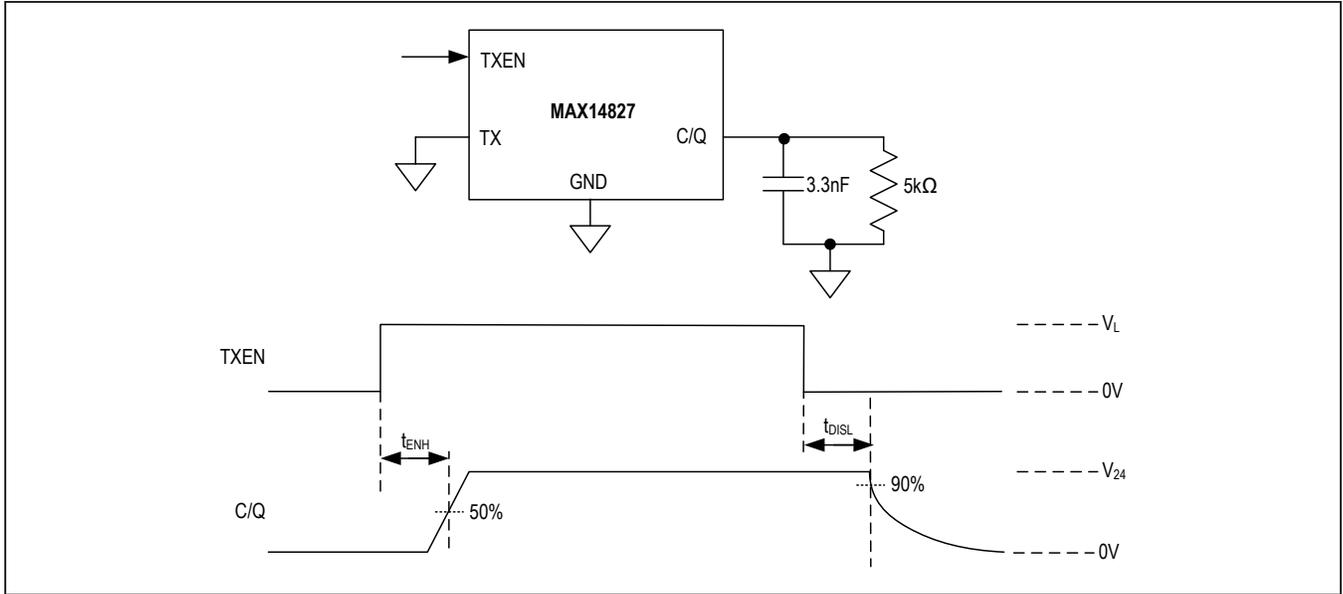


Figure 3. C/Q Driver Enable High and Disable Low Timing

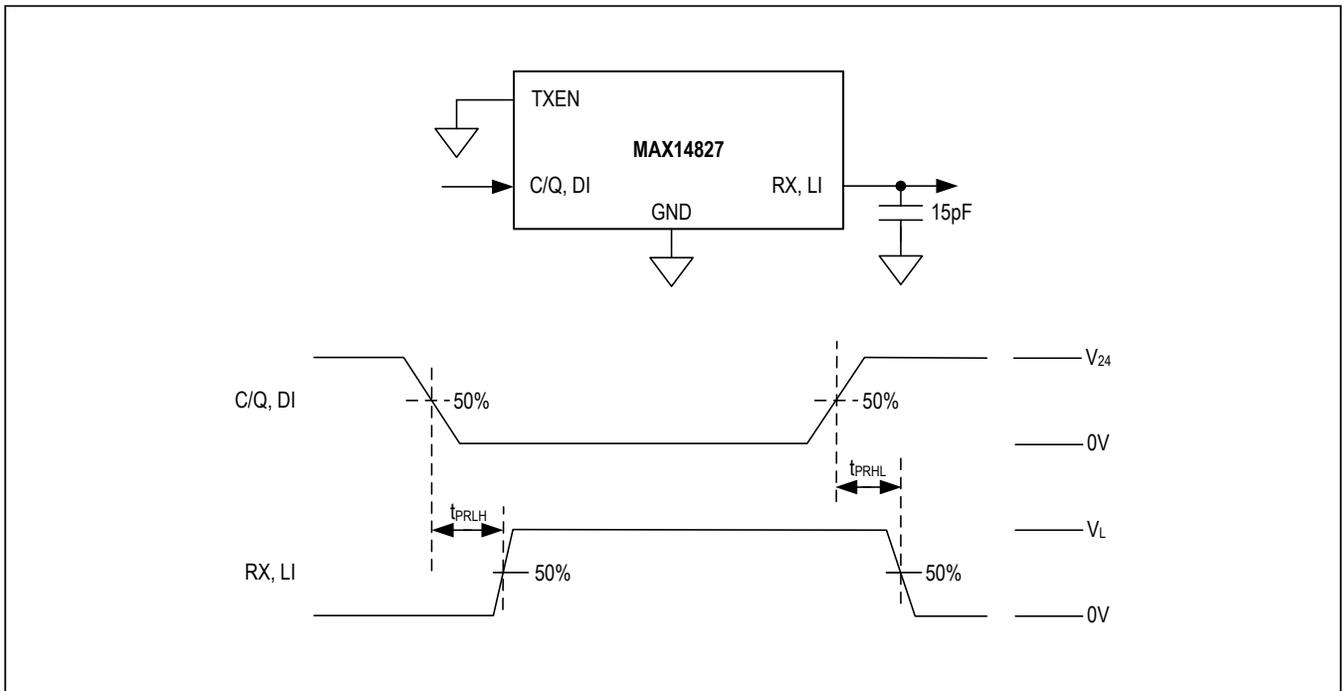


Figure 4. C/Q and DI Receiver Propagation Delays

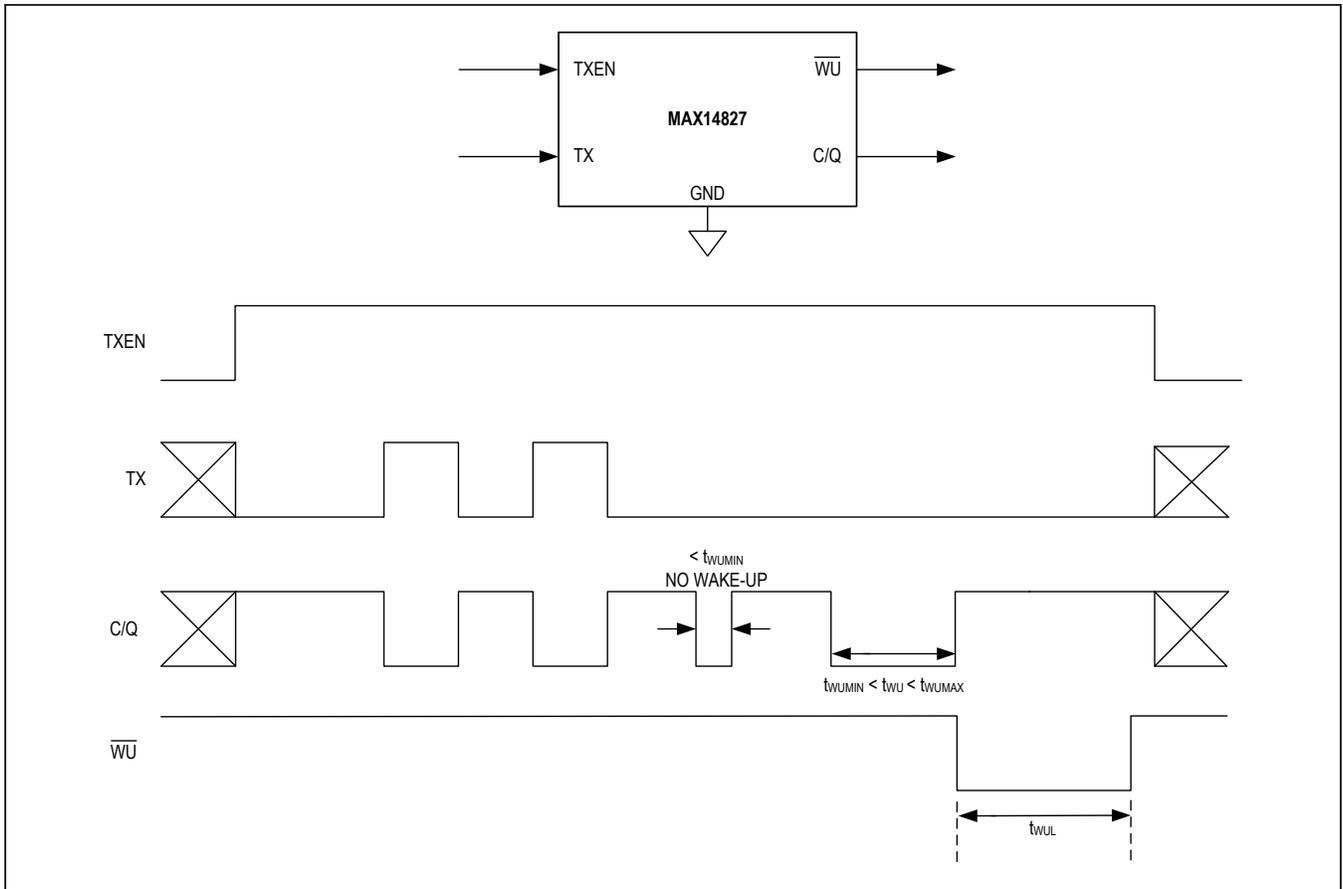


Figure 5. Wake-Up Detection Timing

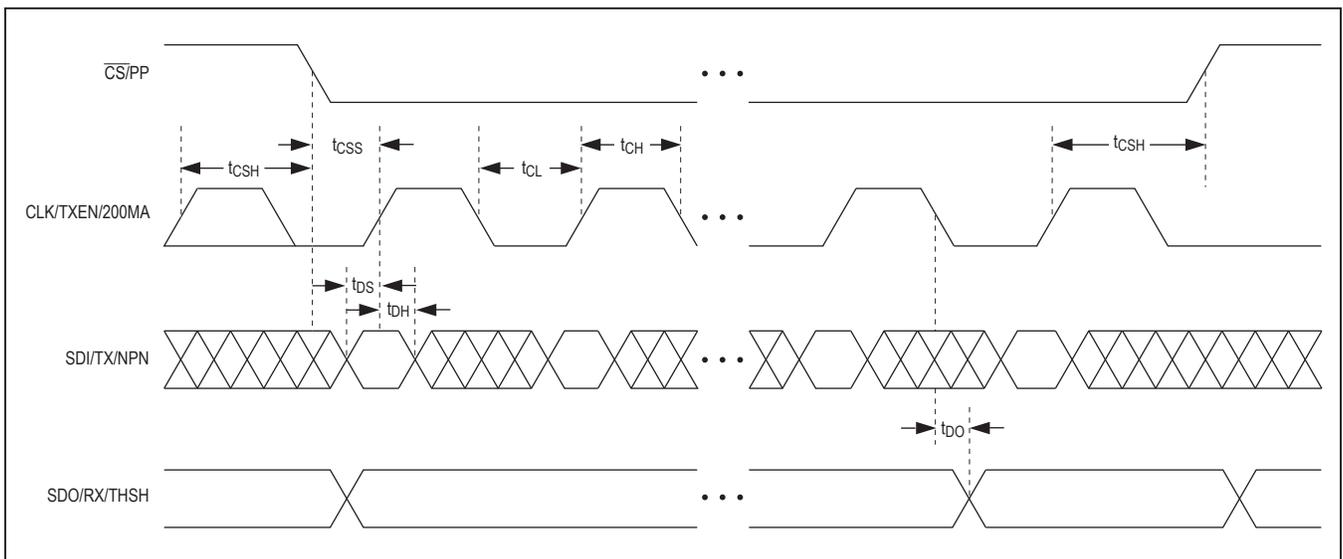
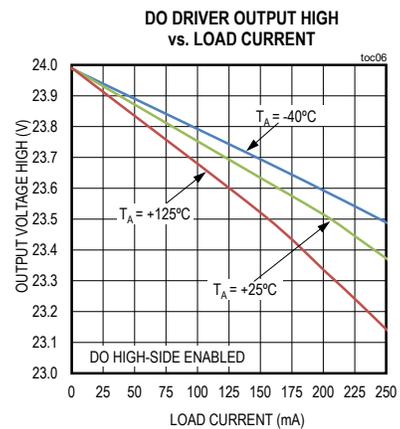
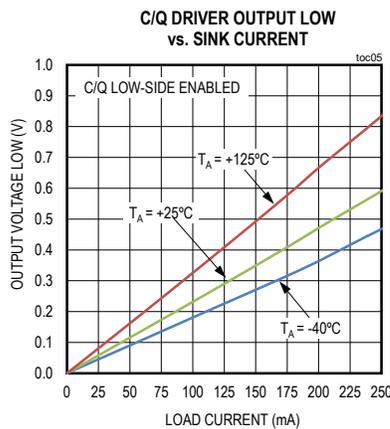
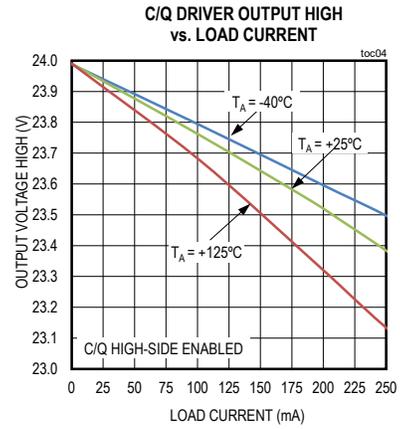
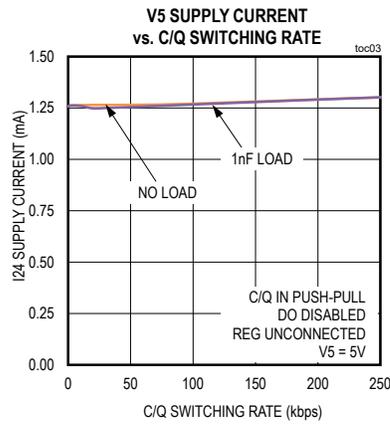
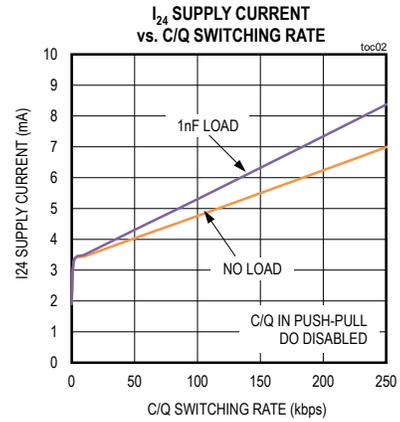
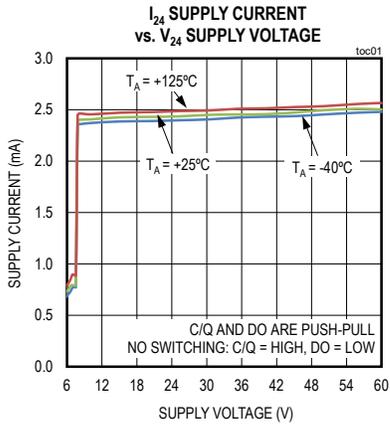


Figure 6. SPI Timing Diagram

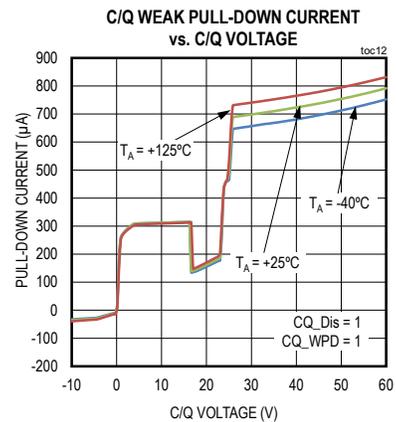
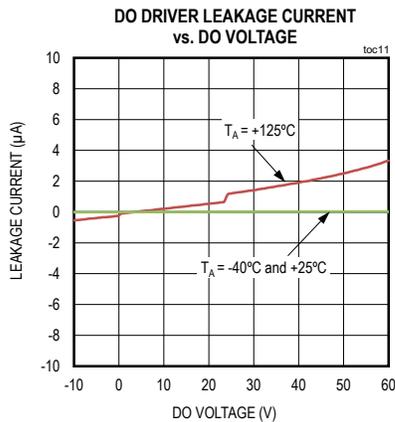
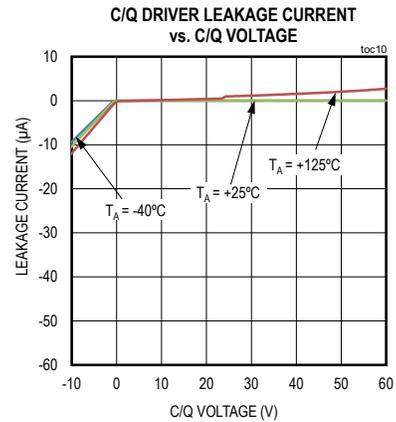
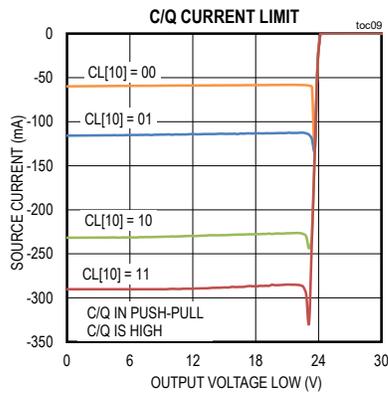
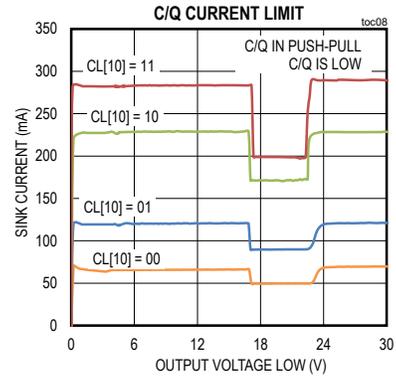
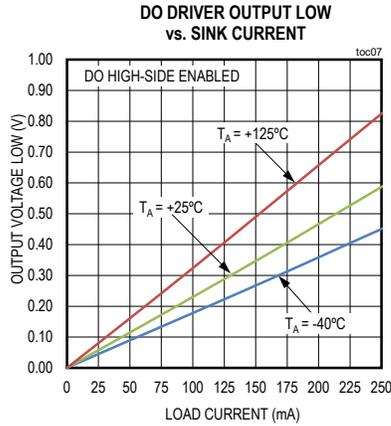
Typical Operating Characteristics

( $V_{24} = 24V$ ,  $V_L = V_{33}$ , REG is shorted to V5, C/Q and DO in push-pull configuration,  $T_A = +25^\circ C$ , unless otherwise noted.)



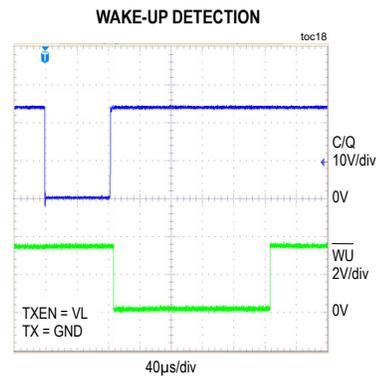
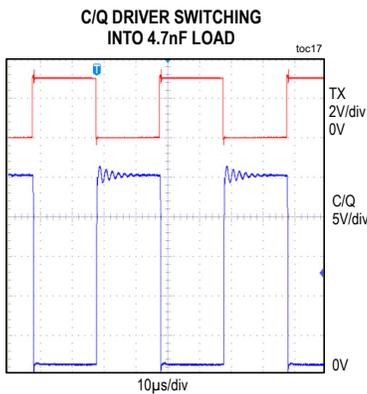
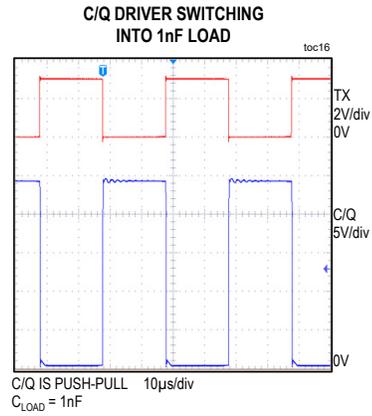
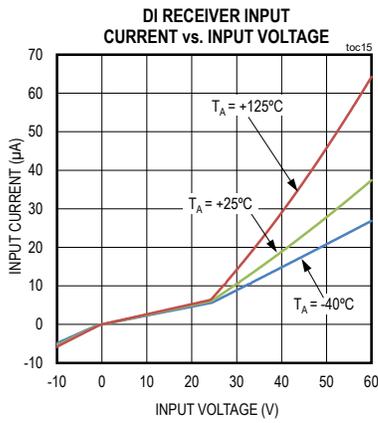
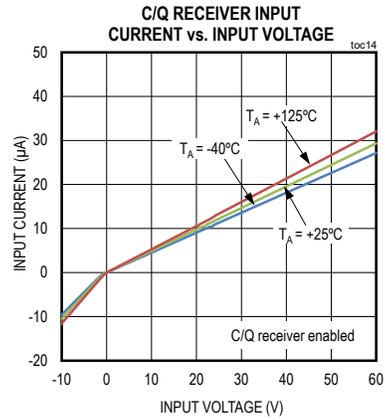
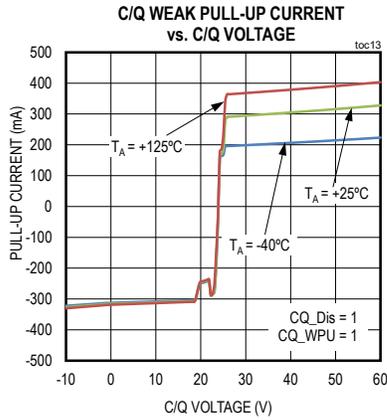
Typical Operating Characteristics (continued)

( $V_{24} = 24V$ ,  $V_L = V_{33}$ , REG is shorted to V5, C/Q and DO in push-pull configuration,  $T_A = +25^\circ C$ , unless otherwise noted.)



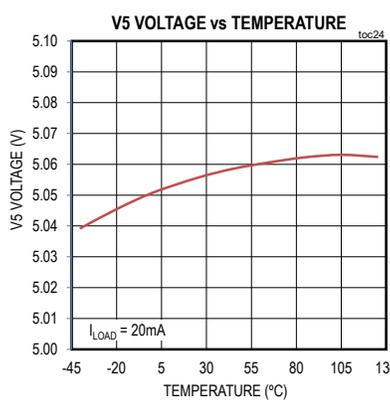
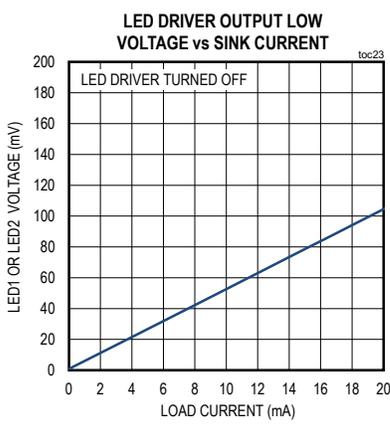
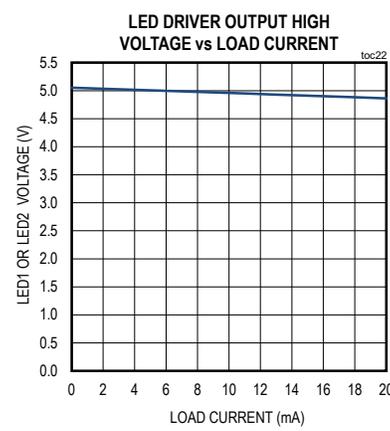
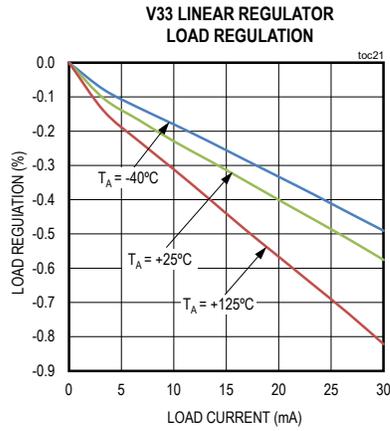
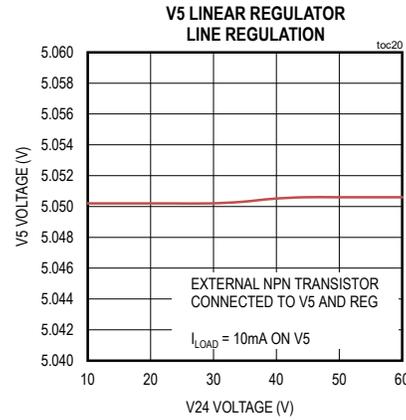
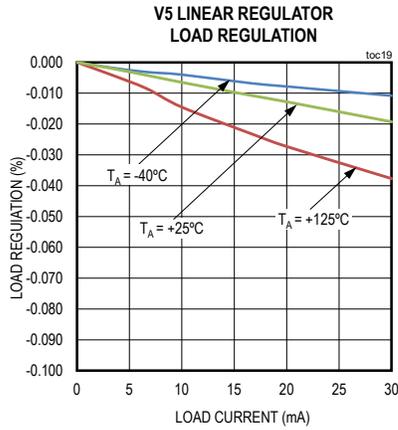
Typical Operating Characteristics (continued)

( $V_{24} = 24V$ ,  $V_L = V_{33}$ , REG is shorted to V5, C/Q and DO in push-pull configuration,  $T_A = +25^\circ C$ , unless otherwise noted.)

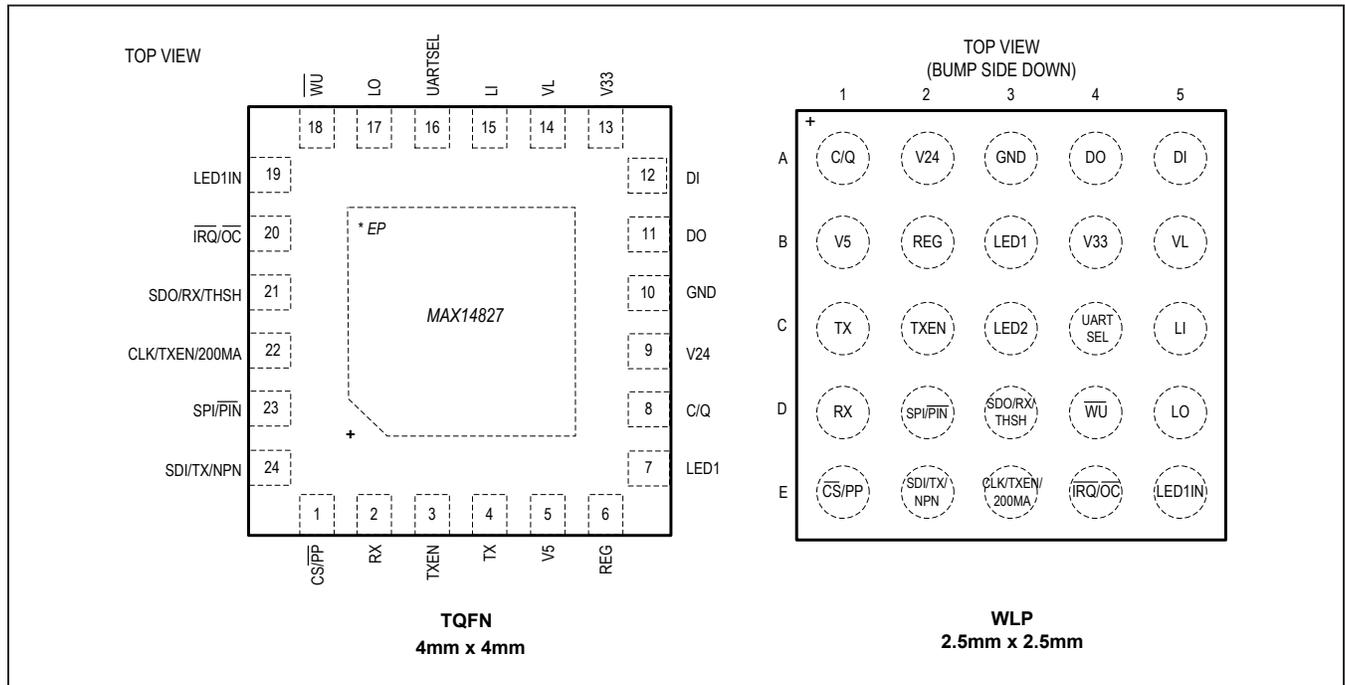


Typical Operating Characteristics

( $V_{24} = 24V$ ,  $V_L = V_{33}$ , REG is shorted to V5, C/Q and DO in push-pull configuration,  $T_A = +25^\circ C$ , unless otherwise noted.)



Pin Configuration



Pin Description

PIN		NAME	PIN DESCRIPTION	FUNCTION		
TQFN	WLP			PARALLEL MODE (SPI/PIN = high)	MULTIPLEXED MODE (SPI/PIN = high)	PIN MODE (SPI/PIN = low)
				UARTSEL = Low	UARTSEL = high	
1	E1	$\overline{CS}/PP$	$\overline{CS}/PP$ Logic Input	SPI active-low chip-select input. Drive $\overline{CS}/PP$ low to start the SPI read/write cycle. Drive $\overline{CS}/PP$ high to end the SPI cycle. UART interface is enabled on RX, TX, and TXEN.	SPI chip-select and UART signal select input. When $\overline{CS}/PP$ is high, the SPI interface is disabled and UART interface mode is enabled on the SDO/RX/THSH, SDI/TX/NPN, and CLK/TXEN/200MA logic pins.	Push-pull select input. Drive $\overline{CS}/PP$ high to enable push-pull mode for the C/Q and DO drivers. Drive $\overline{CS}/PP$ low to select PNP or NPN operation for the drivers.
2	D1	RX	C/Q Receiver Logic Output	RX is the inverse logic of C/Q. RX can be disabled with the SPI interface. RX is high impedance when Rx_Dis = 1.		RX is the inverse logic of C/Q. RX is always active.

## Pin Description (continued)

PIN		NAME	PIN DESCRIPTION	FUNCTION		
TQFN	WLP			PARALLEL MODE (SPI/PIN = high)	MULTIPLEXED MODE (SPI/PIN = high)	PIN MODE (SPI/PIN = low)
				UARTSEL = Low	UARTSEL = high	
3	C2	TXEN	C/Q Driver Enable Logic Input	Drive TXEN high to enable the C/Q driver. See Table 1.	With $\overline{CS}/PP$ low and ENMPX = 0, drive TXEN high to enable C/Q.	Drive TXEN high to enable the C/Q driver. Drive TXEN low to disable the C/Q driver and enable the C/Q receiver.
4	C1	TX	C/Q Driver Communication Input	The logic on the C/Q output is the inverse logic level of the signal on the TX input. See Table 1.	With $\overline{CS}/PP$ low and ENMPX = 0, the logic on the C/Q output is the inverse logic level of the signal on the SDI/TX/NPN input. Signals on TX are ignored. See the Mode Selection table.	The logic on the C/Q output is the inverse logic level of the signal on the TX input when TXEN is high.
5	B1	V5	5V Power-Supply Input/Output	5V must be present on V5 for normal operation. Bypass V5 to GND with a 1 $\mu$ F capacitor. V5 can be supplied by the internal 5V linear regulator or by an external regulator. To use the internal regulator, connect V5 to REG, or to the emitter of an external NPN transistor. To bypass the internal regulator, connect an external 5V supply directly to V5.		
6	B2	REG	5V Regulator Control Output	To use the internal linear regulator, connect REG to V5 or connect REG to the base of an external NPN pass transistor. Leave REG unconnected and connect V5 to an external 5V supply to bypass the internal regulator.		
7	B3	LED1	LED Driver Output 1	LED1 is a 5V logic output. Connect a current-limiting resistor in series between LED1 and the LED to limit the LED current. LED1 can be controlled by driving the LED1IN high or low, of through the SPI interface. Set the LED1b bit high to turn on the LED, clear the LED1b bit to turn off the LED. Alternatively, drive the LED1IN input high to turn on the LED, drive LED1IN low to turn off the LED. See Table 2.	LED1 is a 5V logic output. Connect a current-limiting resistor in series between LED1 and the LED to limit the LED current. Drive the LED1IN input high to turn on the LED, drive LED1IN low to turn off the LED.	
–	C3	LED2	LED Driver Output 2	LED2 is a 5V logic output. Connect a current-limiting resistor in series between LED2 and the LED to limit the LED current. Set the LED2b bit high to turn on the LED, clear the LED2b bit to turn off the LED.	LED2 cannot be controlled in pin-mode. LED2 is off.	

## Pin Description (continued)

PIN		NAME	PIN DESCRIPTION	FUNCTION		
TQFN	WLP			PARALLEL MODE (SPI/PIN = high)	MULTIPLEXED MODE (SPI/PIN = high)	PIN MODE (SPI/PIN = low)
				UARTSEL = Low	UARTSEL = high	
8	A1	C/Q	C/Q Transceiver Output/ Input	The C/Q driver can be controlled and monitored with the logic input/output pins or through the SPI interface. Drive TXEN high to enable the C/Q driver. The logic on the C/Q output is the inverse logic-level of the signal in the TX input. RX is the logic inverse of C/Q.	Drive TXEN high to enable the C/Q driver. The logic on the C/Q output is the inverse logic-level of the signal in the TX input. RX is the logic inverse of C/Q. Configure the C/Q driver with the pin-mode inputs.	
9	A2	V24	Power-Supply Input	Bypass V24 to GND with a 1µF ceramic capacitor as close to the device as possible.		
10	A3	GND	Ground			
11	A4	DO	DO Driver Output	DO is the inverse logic level of the LO input. The DO driver can be enabled/disabled, configured, controlled, and monitored with the logic input/output pins or through the SPI interface.	DO is the inverse logic level of the LO input. Configure the DO driver with the pin-mode inputs. DO cannot be disabled in pin-mode.	
12	A5	DI	DI Receiver Input	The DI receiver can be monitored on the LI output or through the SPI interface. The LI output is the inverse logic-level of the signal on the DI input. Connect a 1kΩ resistor in series with the DI pin.	The LI output is the inverse logic-level of the signal on the DI input. The DI receiver cannot be disabled in pin-mode. Connect a 1kΩ resistor in series with the DI pin.	
13	B4	V33	3.3V Linear Regulator Output	Bypass V33 to GND with a 1µF capacitor as close to the IC as possible. The V33 regulator can be disabled through the SPI interface.	Bypass V33 to GND with a 1µF capacitor as close to the IC as possible. V33 cannot be disabled in pin-mode.	
14	B5	VL	Logic-Level Supply Input	VL defines the logic levels on all of the logic inputs and outputs. Apply a voltage from 2.5V to 5.5V on VL. Bypass VL to GND with a 0.1µF ceramic capacitor.		
15	C5	LI	DI Receiver Logic Output	The LI output is the inverse logic-level of the signal on the DI input. Disable the LI output through the SPI interface. LI is high impedance when the DI_Dis bit is set.	The LI output is the inverse logic-level of the signal on the DI input. LI cannot be disabled in pin-mode.	

Pin Description (continued)

PIN		NAME	PIN DESCRIPTION	FUNCTION		
TQFN	WLP			PARALLEL MODE (SPI/ $\overline{\text{PIN}}$ = high)	MULTIPLEXED MODE (SPI/ $\overline{\text{PIN}}$ = high)	PIN MODE (SPI/ $\overline{\text{PIN}}$ = low)
				UARTSEL = Low	UARTSEL = high	
16	C4	UARTSEL	UART Interface Select Logic Input	Drive UARTSEL low to use RX, TX, and TXEN for UART signaling.	When $\overline{\text{CS}}/\overline{\text{PP}}$ is high, use SDO/RX/THSH, SDI/TX/NPN, and CLK/TXEN/200MA for UART signaling.	UARTSEL is inactive when SPI/ $\overline{\text{PIN}}$ is low.
17	D5	LO	DO Driver Logic Input	The logic on the DO output is the inverse logic-level of the signal on the LO input. Configure, control, and monitor the DO output through the logic pins or through the SPI interface.		The logic on the DO output is the inverse logic-level of the signal on the LO input. Configure the DO driver with the pin-mode inputs.
18	D4	$\overline{\text{WU}}$	Wake-Up Request Push-Pull Output	$\overline{\text{WU}}$ asserts low for 200 $\mu\text{s}$ when an IO-Link 80 $\mu\text{s}$ wake-up condition is detected on the C/Q line.		
19	E5	LED1IN	LED1 Driver Logic Input	Drive LED1IN high or low to enable/disable the LED1 driver. The LED1 driver can also be controlled through the SPI interface. See Table 2.		Drive LED1IN high to turn on the LED connected to LED1. Drive LED1IN low to turn the LED driver off.
20	E4	$\overline{\text{IRQ}}/\overline{\text{OC}}$	Open-Drain Interrupt/Over-current Output	$\overline{\text{IRQ}}/\overline{\text{OC}}$ asserts when any bit in the INTERRUPT register is set. $\overline{\text{IRQ}}/\overline{\text{OC}}$ deasserts when the INTERRUPT register is read.		$\overline{\text{IRQ}}/\overline{\text{OC}}$ asserts low when the load current on the C/Q or DO output exceeds the set current limit.
21	D3	SDO/RX/THSH	SPI Serial Data Output/RX Logic Output/Thermal Shutdown Indicator	SPI serial data output	When $\overline{\text{CS}}/\overline{\text{PP}}$ is high, the SPI interface is disabled and UART interface mode is enabled. SDO/RX/THSH is the logic inverse of C/Q.	SDO/RX/THSH asserts low when the IC enters thermal shutdown. SDO/RX/THSH deasserts when the device returns to normal operation.

## Pin Description (continued)

PIN		NAME	PIN DESCRIPTION	FUNCTION		
TQFN	WLP			PARALLEL MODE (SPI/ $\overline{\text{PIN}}$ = high)	MULTIPLEXED MODE (SPI/ $\overline{\text{PIN}}$ = high)	PIN MODE (SPI/ $\overline{\text{PIN}}$ = low)
				UARTSEL = Low	UARTSEL = high	
22	E3	CLK/ TXEN/ 200MA	SPI Clock Input/ UART TXEN Input/ Current Limit Setting Input	SPI clock input	When $\overline{\text{CS}}/\text{PP}$ is high, the SPI interface is disabled and UART interface mode is enabled. Drive CLK/TXEN/200MA high to enable the C/Q driver.	Drive CLK/TXEN/200MA high to enable a 200mA current limit on the C/Q and DO driver outputs. Drive CLK/TXEN/200MA low to set the current limit for the driver outputs to 100mA.
23	D2	SPI/ $\overline{\text{PIN}}$	SPI or Pin- Mode Select Input	Drive SPI/ $\overline{\text{PIN}}$ high for SPI or UART interface operation. Drive SPI/ $\overline{\text{PIN}}$ low for pin-mode operation.		
24	E2	SDI/TX/ NPN	SPI Serial Data Input/ TX Logic Input/ NPN Driver Mode Select Input	SPI serial data input	When $\overline{\text{CS}}/\text{PP}$ is high, the SPI interface is disabled and UART interface mode is enabled. Drive SDI/TX/NPN to switch C/Q. C/Q is the logic inverse of the SDI/TX/NPN input.	Drive SDI/TX/NPN high to set the C/Q and DO driver outputs in NPN mode. Drive SDI/TX/NPN low to set the driver outputs in PNP mode. SDI/TX/NPN is ignored when the $\overline{\text{CS}}/\text{PP}$ input is high.
EP	–	EP	Exposed pad. Connect to ground. Not intended as the main ground connection.			

**Table 1. C/Q and DO Control**

SPI/PIN	TXEN	TX or LO	CQ_Dis or DO_Dis	CQ_Q or DO_Q	NPN MODE		PNP MODE		PP MODE		
					C/Q	DO	C/Q	DO	C/Q	DO	
L	L	L	-	-	Z	Z	Z	H	Z	H	
		H	-	-	Z	L	Z	Z	Z	L	
	H	L	-	-	Z	Z	H	H	H	H	
		H	-	-	L	L	Z	Z	L	L	
H	L	L	0	0	Z	Z	Z	H	Z	H	
		L	0	1	Z	Z	H	H	H	H	
		H	0	0	Z	L	Z	Z	Z	L	
		H	0	1	Z	Z	H	H	H	H	
	H	L	0	0	Z	Z	H	H	H	H	
		L	0	1	Z	Z	H	H	H	H	
		H	0	0	L	L	Z	Z	L	L	
		H	0	1	Z	Z	H	H	H	H	
	X	X	X	1	X	Z	Z	Z	Z	Z	Z

X = Don't care, Z = High impedance

**Table 2: LED1 Configuration**

LED1IN	LED1b BIT	LED1 DRIVER STATUS
L	0	OFF
	1	ON
H	0	ON
	1	ON

**Table 3. Driver NPN, PNP, PP Selection in Pin-Mode**

SPI/PIN	CS/PP	SDI/TX/NPN	C/Q AND DO DRIVER MODE
L	L	L	PNP
L	L	H	NPN
L	H	L	PUSH-PULL
L	H	H	PUSH-PULL
H	X	X	C/Q and DO Modes are set with the SPI interface

## Detailed Description

The MAX14827 is an industrial sensor output driver/IO-Link device transceiver. The IC integrates the high voltage functions commonly found in sensors, including two 24V line driver and two on-board linear regulators (LDOs). The MAX14827 can be configured and monitored either through the SPI interface or by setting logic interface pins.

The MAX14827 features multiple programmable functions that allow the user to optimize operation and power dissipation for various loads and application scenarios.

The integrated 3.3V and 5V LDOs provide the power needed for low noise analog and logic supply rails.

### SPI, UART, or Pin-Mode Interface

#### Pin-Mode

The MAX14827 provides a selectable SPI or pin interface to configure and monitor device operation. Drive the SPI/PIN input high to use the SPI. Drive SPI/PIN low to use the pin interface (pin-mode control).

When operating in pin mode, the following functionality is set and cannot be changed:

- RX and DI are enabled (cannot be disabled)
- RX deglitch filter is enabled
- Weak pull-ups/pull-downs on C/Q and DO are disabled
- Autoretry functionality is disabled
- The blanking time on C/Q and DO is 128 $\mu$ s

#### SPI Operation (Parallel Operating Mode)

When the MAX14827 is operated in SPI mode, an external UART can be connected to separate UART interface pins (TX, RX, TXEN). This is called the parallel SPI/UART operating mode. This is the common approach used when the microcontroller offers a UART and a separate SPI port in the Typical Applications circuit. Drive UARTSEL low for operation in parallel mode.

#### SPI Operation (Multiplexed Mode)

In cases where only one microcontroller serial port is available with both SPI and UART functions, the MAX14827 can be operated in multiplexed SPI/UART mode. This is feasible in IO-Link operation due to the defined idle times in the IO-Link cycle time. In multiplexed mode, the UART and SPI pins are shared. Two operating modes are available in multiplexed mode, as selected by the ENMPX bit.

When ENMPX = 0, UART and SPI operation are selected by setting the  $\overline{\text{CS}}/\text{PP}$  input. In this mode the SPI interface

is active when  $\overline{\text{CS}}/\text{PP}$  is low and UART operation when  $\overline{\text{CS}}/\text{PP}$  is high.

When ENMPX = 1, UART and SPI operations are selected by setting the UARTSEL input. To avoid glitches on C/Q, CLK/TXEN/200MA and SDI/TX/NPN are sampled on the falling edge of UARTSEL in this mode. See Mode Selection Table for more information.

When entering multiplexed mode, set TXEN low and TX high to disable the driver.

$\overline{\text{IRQ}}/\text{OC}$  is active in both multiplexed modes during UART communication.

### 24V Interface

The MAX14827 features an IO-Link transceiver interface capable of operating with voltages up to 60V. This is the 24V interface and includes the C/Q input/output, the logic-level digital output (DO), the logic-level digital input (DI), and the V24 supply.

The MAX14827 features selectable push-pull, high-side (PNP), or low-side (NPN) switching drivers at C/Q and DO.

#### Configurable Drivers (Pin-Mode)

In pin-mode, use SDI/TX/NPN and  $\overline{\text{CS}}/\text{PP}$  inputs to configure the C/Q and DO drivers in push-pull, PNP, or NPN modes (Table 3). In this mode, toggle TXEN, TX, and LO to switch the C/Q and DO outputs.

#### Configurable Drivers (SPI Mode)

In SPI operation, the C/Q and DO drivers can be configured independently. Set the bits in the CQConfig register to configure the C/Q driver, enable/disable the weak pull-up and pull-down currents on C/Q. Set the bits in the DIOConfig register to configure the DO driver and enable/disable the weak pull-up and pull-down currents on DO. The C/Q and DO drivers can be disabled by setting the CQ\_Dis and DO\_Dis bits. Driver outputs are high impedance and power dissipation is reduced when these bits are set. See the *Register Functionality* section for more information on configuring the drivers.

For IO-Link operation, TX, TXEN, and RX are the UART interface to control C/Q communication. Set CQ\_Dis = CQ\_Q = 0 and drive TX and TXEN inputs for C/Q driver control.

For lower rate switching on the C/Q and DO drivers, register bits can be used for C/Q and DO control. For bit control, drive TXEN, TX, and LO high and use the CQ\_Q and DO\_Q bits to control the C/Q and DO driver states. The CQ\_Dis and DO\_Dis bits are used to enable/disable the drivers in this mode.

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SPI is a trademark of Motorola, Inc.*

### C/Q Driver Enable/Disable

In pin-mode, the C/Q driver is enabled/disabled with the TXEN input. Drive TXEN high to enable the C/Q driver. C/Q is the logic inverse of the TX input.

In SPI mode, the C/Q driver can also be enabled/disabled, configured, and controlled in the CQConfig register.

### C/Q Current Limit

The C/Q driver is optimized for driving large capacitive loads and dynamic impedances like incandescent lamps. In pin-mode, the driver current limit is selectable by setting the CLK/TXEN/200MA input high or low. Set CLK/TXEN/200MA low for 100mA maximum load current. Set CLK/TXEN/200MA high for a 200mA maximum load current.

In SPI operation, the maximum driver current limit is selectable as 50mA, 100mA, 200mA, or 250mA by setting the CL1 and CL0 bits in the CURRLIM register.

### C/Q Driver Fault Detection

The MAX14827 senses a fault condition on the C/Q driver when it detects a short circuit for longer than the blanking time. A short condition exists when the C/Q driver's load current exceeds the current limit. In SPI mode, both the current limit and blanking time may be configured.

In pin-mode, the  $\overline{\text{IRQ/OC}}$  output asserts low when a short circuit fault occurs on C/Q or DO. In SPI mode, the C/QFault and C/QFaultInt bits are set and  $\overline{\text{IRQ/OC}}$  asserts.

When a short-circuit event occurs on C/Q, the driver can either be set to continue supplying the selected current until the device enters thermal shutdown or to enter autoretry mode when an overcurrent event occurs. In autoretry mode the driver is automatically disabled after the current blanking time and is then re-enabled.

### C/Q Receiver Output (RX)

RX is the output of the C/Q receiver. RX is the inverse logic of the C/Q input.

In pin-control mode, the C/Q receiver is always on.

In SPI mode, the receiver can be disabled by setting the Rx\_Dis bit in the CQConfig register. RX is high impedance when Rx\_Dis is set. Note that the CQLvl bit in the Status register is invalid when the Rx\_Dis bit is set.

When operating in multiplexed mode, SDO/RX/THSH is the output of the C/Q receiver. In this mode, SDO/RX/THSH is high impedance when  $\overline{\text{CS/PP}}$  is high and Rx\_Dis bit is set.

### C/Q Receiver Threshold

The IO-Link standard defines device operation with a sensor supply between 18V and 30V. Industrial sensors, however, commonly operate with supply voltages as low as 9V. The MAX14827 C/Q receiver supports operation with lower supply voltages by scaling the receiver thresholds when V24 is less than 18V ( $V_{24} < 18V$ ).

### DO Driver

In pin-mode, the DO driver is always enabled. DO is the logic inverse of the LO input.

In SPI mode, the DO driver can be enabled/disabled, configured, and controlled in the DIOConfig register.

### DO Current Limit

The DO driver is optimized for driving large capacitive loads and dynamic impedances like incandescent lamps. In pin-control mode, the driver current limit is selectable by setting the CLK/TXEN/200MA input high or low. Set CLK/TXEN/200MA low for 100mA maximum load current. Set CLK/TXEN/200MA high for a 200mA maximum load current.

In SPI operation, the maximum driver current limit is selectable as 50mA, 100mA, 200mA, or 250mA by setting the CL1 and CL0 bits in the CURRLIM register.

### DO Fault Detection

The MAX14827 senses a fault condition on the DO output when it detects a short circuit for longer than the blanking time. A short condition exists when the DO driver's load current exceeds the current limit. In SPI mode, both the current limit and blanking time may be configured.

In pin-mode, the  $\overline{\text{IRQ/OC}}$  output asserts low when a short circuit fault occurs on C/Q or DO. In SPI mode, the DoFault and DoFaultInt bits are set and  $\overline{\text{IRQ/OC}}$  asserts.

When a short-circuit event occurs on DO, the driver can either be set to continue supplying the selected current until the device enters thermal shutdown or to enter autoretry mode when an overcurrent event occurs. In autoretry mode the driver is automatically disabled after the current blanking time and is then re-enabled.

### DO and C/Q Tracking

In SPI mode, the DO driver can be configured to track the C/Q driver. Set the CQDOPar bit in the CQConfig register to enable this functionality. When the DO driver is set to track C/Q, both C/Q and DO switch as a function of the TX and TXEN inputs or CQ\_Q bit.

In pin-mode, or when CQDOPar is 0, C/Q and DO operate independently.

### Reverse-Polarity Protection

The MAX14827 is protected against reverse-polarity connections on V24, C/Q, DO, DI, and GND. Any combination of these pins can be connected to DC voltages up to 65V (max), resulting in a current flow of less than 1mA.

Ensure that the maximum voltage between any of these pins does not exceed 65V.

### Driver Short-Circuit Detection

The MAX14827 monitors the DO and C/Q driver outputs for overcurrent and driver overheating conditions.

In pin-mode, the driver short-circuit current limit is set with the CLK/TXEN/200mA input.  $\overline{\text{IRQ/OC}}$  asserts when an overcurrent or overheating condition occurs on either the C/Q or DO driver.  $\overline{\text{IRQ/OC}}$  deasserts when the overcurrent or overheating condition is removed.

In SPI mode, the DO and C/Q are independently monitored. Driver current limits for both drivers are set using the CL1 and CL0 bits in the CURRLIM register. When an overcurrent or overheating condition occurs on C/Q, the CQFault and CQFaultInt bits are set and  $\overline{\text{IRQ/OC}}$  asserts. When an overcurrent or overheating condition occurs on DO, the DOFault and DOFaultInt bits are set. The CQFault and DOFault bits are cleared as soon as the overcurrent or overheating conditions on the C/Q and DO drivers are removed.  $\overline{\text{IRQ/OC}}$  deasserts and the CQFaultInt and DOFaultInt bits are cleared only when the INTERRUPT register is read.

### 5V and 3.3V Linear Regulators

The MAX14827 includes two internal regulators to generate 5V (V5) and 3.3V (V33).

The V5 regulator is capable of driving external loads up to 30mA, including device and 3.3V LDO current consumption. To drive larger loads, use an external pass transistor to generate the required 5V. When using an external transistor, connect REG to the base of the transistor to regulate the voltage and connect V5 to the emitter ([Figure 10](#)).

When the internal 5V linear regulator is not used, V5 is the supply input for the internal analog and digital functions and must be supplied externally. Ensure that V5 is present for normal operation.

The 3.3V regulator is capable of driving external loads up to 30mA. In SPI mode, the 3.3V LDO can be enabled/disabled by setting the V33Dis bit in the Mode register.

V5 and V33 are not protected against short circuits.

### Power-Up

The C/Q and DO driver outputs are high impedance when V24, V5, VL, and/or V33 voltages are below their respective undervoltage thresholds during power-up.

The drivers are automatically disabled if V24, V5, or VL falls below its threshold.

### Low Voltage and Undervoltage Detection

In SPI mode, the device monitors the V24 supply for low voltage and undervoltage conditions. Low-voltage warnings must be enabled in the MODE register.

When V24 falls below the 16V (typ) low-voltage warning threshold, the V24W bit in the STATUS register is set. If V24WEn is set to 1, the V24WInt interrupt bit is also set and  $\overline{\text{IRQ/OC}}$  asserts.

When V24 falls below the 7.4V (typ) undervoltage lockout (UVLO) threshold, the UV24 bit in the STATUS register is set. Similarly, the UV24Int bit in the INTERRUPT register is set and  $\overline{\text{IRQ/OC}}$  asserts. UVLO monitoring and interrupts cannot be disabled.

### Wake-Up Detection

The MAX14827 detects an IO-Link wake-up condition on the C/Q line in push-pull, high-side (PNP), or low-side (NPN) operation modes. A wake-up condition is detected when the C/Q output is shorted for 80μs (typ). WU pulses low for 200μs (typ) when the device detects a wake-up pulse on C/Q ([Figure 5](#)).

In SPI mode, the Wulnt bit in the INTERRUPT register is set and  $\overline{\text{IRQ/OC}}$  asserts when an IO-Link wake-up event is detected.

Wake-up detection can be disabled in SPI mode by setting the WU\_Dis bit in the MODE register to 1. Wake-up detection cannot be disabled in pin-mode.

The device includes a wake-up detection algorithm to avoid false wake-up detection on C/Q. The false wake-up blanking time is defined by the current limit blanking time. In pin-mode, this is 128μs. In SPI-mode, this is set by the CL\_BL0 and CL\_BL1 bits in the CURRLIM register.

### Thermal Protection and Considerations

The internal LDOs and drivers can generate more power than the package for the devices can safely dissipate. Ensure that the driver and LDO loading is less than the package can dissipate. Total power dissipation for the device is calculated using the following equation:

$$P_{\text{TOTAL}} = P_{\text{C/Q}} + P_{\text{DO}} + P_{\text{V5}} + P_{\text{V33}} + P_{\text{P24}} + (2 \times P_{\text{PU}}) + (2 \times P_{\text{PD}})$$

where  $P_{C/Q}$  is the power generated in the C/Q driver,  $P_{DO}$  is the power dissipated by the DO driver,  $P_{V5}$  and  $P_{V33}$  are the power generated by the LDOs,  $P_{24}$  is the quiescent power generated by the device, and  $P_{PU}$  and  $P_{PD}$  are the power generated in the C/Q and DO weak pullup/pulldown current sources/sinks, respectively.

Ensure that the total power dissipation is less than the limits listed in the [Absolute Maximum Ratings](#) section.

Use the following to calculate the power dissipation (in mW) due to the C/Q driver:

$$P_{C/Q} = [I_{C/Q(\max)}]^2 \times R_O$$

where  $R_O$  driver on-resistance.

Calculate the internal power dissipation of the DO driver using the following equation:

$$P_{DO} = [I_{DO(\max)}]^2 \times R_O$$

where  $R_O$  driver on-resistance.

Calculate the power dissipation in the 5V LDO,  $V_5$ , using the following equation:

$$P_5 = (V_{24} - V_5) \times I_5$$

where  $I_5$  includes the  $I_{33}$  current sourced from  $V_{33}$ .

Calculate the power dissipated in the 3.3V LDO,  $V_{33}$ , using the following equation:

$$P_{33} = 1.7V \times I_{LOAD33}$$

Calculate the quiescent power dissipation in the device using the following equation:

$$P_{24} = I_{24(\max)} \times V_{24(\max)}$$

If the weak current sinks/sources are enabled, calculate their associated power dissipation as:

$$P_{PD} = I_{PD(\max)} \times V_{C/Q(\max)}$$

$$P_{PU} = I_{PU(\max)} \times [V_{24} - V_{C/Q}](\max)$$

### Overtemperature Warning

In SPI mode, the device generates interrupts when the junction temperature of any of the drivers (C/Q or DO) exceeds +140°C (typ) warning threshold. The TempW bit in the STATUS register is set and the TempWInt in the INTERRUPT register is set and  $\overline{IRQ/OC}$  asserts under these conditions.

The TempW bit is cleared when the die temperature falls to +125°C. The INTERRUPT register must be read to clear the TempWInt bit and deassert  $\overline{IRQ/OC}$ .

The device continues to operate normally unless the die temperature reaches the +165°C thermal shutdown threshold, when the device enters thermal shutdown.

The device does not generate overtemperature warnings when operating in pin-mode.

### Thermal Shutdown

The C/Q and DO drivers, and the  $V_5$  and  $V_{33}$  regulators are automatically switched off when the junction temperature exceeds the +165°C (typ) thermal shutdown threshold. SPI communication and the internal regulators are not disabled during thermal shutdown. In SPI mode, the ThShut bit in the STATUS register and the ThShutInt in the INTERRUPT register are set.

Regulators are automatically switched on when the internal die temperature falls below the thermal shutdown threshold plus hysteresis. If the internal  $V_5$  regulator is used, the internal registers return to their default state when the  $V_5$  regulator is switched back on.

Mode Selection Table

OPERATING MODE	SPI/ PIN	UARTSEL	ENMPX Bit	$\overline{CS}/PP$	PIN NAME	PIN FUNCTION	FUNCTION				
PIN	L	X	X	LOW OR HIGH	SDI/TX/NPN	NPN	Parallel configuration/monitoring				
					SDO/RX/THSH	THSH	Parallel configuration/monitoring				
					CLK/TXEN/200MA	200MA	Parallel configuration/monitoring				
					$\overline{CS}/PP$	PP	Parallel configuration/monitoring				
					$\overline{IRQ}/OC$	$\overline{OC}$	Parallel configuration/monitoring				
					RX	C/Q RX	Parallel configuration/monitoring/ UART communication				
					TX	C/Q TX	Parallel configuration/monitoring/ UART communication				
					TXEN	C/Q TXEN	Parallel configuration/monitoring/ UART communication				
PARALLEL UART + SPI	H	L	0	LOW OR HIGH	SDI/TX/NPN	SDI	SPI configuration/monitoring				
					SDO/RX/THSH	SDO	SPI configuration/monitoring				
					CLK/TXEN/200MA	CLK	SPI configuration/monitoring				
					$\overline{CS}/PP$	CS	SPI configuration/monitoring				
					$\overline{IRQ}/OC$	$\overline{IRQ}$	SPI configuration/monitoring				
					RX	C/Q RX	UART communication				
					TX	C/Q TX	UART communication				
					TXEN	C/Q TXEN	UART communication				
MULTIPLEXED UART/SPI	H	H	0	L	SDI/TX/NPN	SDI	SPI configuration/monitoring				
					SDO/RX/THSH	SDO	SPI configuration/monitoring				
					CLK/TXEN/200MA	CLK	SPI configuration/monitoring				
					$\overline{CS}/PP$	LOW	SPI configuration/monitoring				
					$\overline{IRQ}/OC$	$\overline{IRQ}$	SPI configuration/monitoring				
					RX	C/Q RX	UART communication				
					TX	C/Q TX	UART communication				
									TXEN	C/Q TXEN	UART communication
								H	SDI/TX/NPN	C/Q TX	UART communication
									SDO/RX/THSH	C/Q RX	UART communication
									CLK/TXEN/200MA	C/Q TXEN	UART communication
									$\overline{CS}/PP$	HIGH	
									$\overline{IRQ}/OC$	$\overline{IRQ}$	SPI configuration/monitoring
									RX	C/Q RX	Active
				TX	C/Q TX	Ignored					
									TXEN	C/Q TXEN	Ignored

## Mode Selection Table (continued)

OPERATING MODE	SPI/ PIN	UARTSEL	ENMPX Bit	$\overline{\text{CS}}/\text{PP}$	PIN NAME	PIN FUNCTION	FUNCTION	
MULTIPLEXED UART/SPI	H	0	1	LOW OR HIGH	SDI/TX/NPN	SDI	SPI configuration/monitoring	
					SDO/RX/THSH	SDO	SPI configuration/monitoring	
					CLK/TXEN/200MA	CLK	SPI configuration/monitoring	
					$\overline{\text{CS}}/\text{PP}$	$\overline{\text{CS}}$	SPI configuration/monitoring	
					$\overline{\text{IRQ}}/\text{OC}$	$\overline{\text{IRQ}}$	SPI configuration/monitoring	
					RX		Active	
					TX		Ignored	
					TXEN		Ignored	
	1					SDI/TX/NPN	C/Q TX	UART communication
						SDO/RX/THSH	C/Q RX	UART communication
						CLK/TXEN/200MA	C/Q TXEN	UART communication
						$\overline{\text{CS}}/\text{PP}$		Not used
						$\overline{\text{IRQ}}/\text{OC}$	$\overline{\text{IRQ}}$	SPI monitoring
						RX		Active
						TX		Ignored
						TXEN		Ignored

## Register Functionality

The devices have four 8-bit-wide registers for configuration and monitoring ([Table 1](#)).

**Table 4. Register Summary**

REGISTER	ADD	R/W	BIT 7	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0
INTERRUPT	00h	R	ThShutInt	WuInt	DoFaultInt	CQFaultInt	V24WInt	UV24Int	-	TempWInt
STATUS	01h	R	ThShut	DiLvl	DoFault	CQFault	V24W	UV24	CQLvl	TempW
MODE	02h	R/W	RST	WU_Dis	V33_Dis	ENMPX	V24WEn	CQFil	LED2b	LED1b
CURRLIM	03h	R/W	CL1	CL0	CLDis	CL_BL1	CL_BL0	TAr1	TAr0	ArEn
CQConfig	04h	R/W	Rx_Dis	CQ_WPD	CQ_WPU	CQDOPar	CQ_NPN	CQ_PP	CQ_Q	CQ_Dis
DIOConfig	05h	R/W	-	DO_WPD	DO_WPU	DO_AV	DO_NPN	DO_PP	DO_Q	DO_Dis

## INTERRUPT Register [A2, A1, A0] = [000]

Bit	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Bit Name	ThShutInt	WuInt	DoFaultInt	CQFaultInt	V24WInt	UV24Int	-	TempWInt
Read/Write	R	R	R	R	R	R	R	R
POR State	0	0	0	0	0	0	0	0
Reset Upon Read	N	N	N	N	N	N	N	N

The INTERRUPT register reflects current state of various fault conditions. The  $\overline{\text{IRQ/OC}}$  output asserts when any of the bits in the INTERRUPT register is set. INTERRUPT register bits are latched and are not cleared when the initiating condition is removed. Reading the INTERRUPT register clears all the bits and deasserts  $\overline{\text{IRQ/OC}}$ .  $\overline{\text{IRQ/OC}}$  reasserts only when another fault condition occurs.

BIT	NAME	DESCRIPTION
7	ThShutInt	<p><b>Thermal Shutdown Interrupt</b></p> <p>1: This bit is set when the MAX14827 has entered thermal shutdown mode. Once set, this bit is not cleared until the register is read. The current status of the thermal shutdown condition can be read in the Status register.</p> <p>0: The MAX14827 is not in thermal shutdown.</p>
6	WuInt	<p><b>Wake-Up Event Interrupt</b></p> <p>1: This bit is set when an IO-Link wake-up condition is detected on the C/Q line.</p> <p>0: No wake-up condition is detected.</p> <p>The wake-up interrupt can be disabled by setting the WuDis bit to 1.</p>

**INTERRUPT Register [A2, A1, A0] = [000] (continued)**

BIT	NAME	DESCRIPTION
5	DoFaultInt	<p><b>DO Driver Fault Interrupt</b></p> <p>1: This bit is set when a fault occurs on the DO driver (over current or over heating). Once set, this bit is not cleared until the register is read. The current status of the thermal shutdown condition can be read in the Status register.</p> <p>0: No fault on the DO driver.</p>
4	CQ_FaultInt	<p><b>C/Q Driver Fault Interrupt</b></p> <p>1: This bit is set when a fault occurs on the C/Q driver (over current or over heating). Once set, this bit is not cleared until the register is read. The current status of the thermal shutdown condition can be read in the Status register.</p> <p>0: No fault on the C/Q driver.</p>
3	V24WInt	<p><b>V24 Low Voltage Warning Interrupt</b></p> <p>1: This bit is set when <math>V_{24}</math> falls below the IO-Link low-voltage warning threshold fault (<math>V_{24} &lt; V_{24W}</math>). Once set, this bit is not cleared until the register is read. The current status of the thermal shutdown condition can be read in the Status register.</p> <p>0: <math>V_{24}</math> is greater than the low-voltage warning threshold.</p>
2	UV24Int	<p><b>V24 Supply Undervoltage Interrupt</b></p> <p>1: This bit is set when <math>V_{24}</math> falls below the UVLO threshold (<math>V_{24} &lt; V_{24UVLO}</math>). Once set, this bit is not cleared until the register is read. The current status of the thermal shutdown condition can be read in the Status register.</p> <p>0: <math>V_{24}</math> is greater than the UVLO threshold.</p>
1	—	This bit is not used.
0	TempWInt	<p><b>Overtemperature Warning Interrupt</b></p> <p>1: This bit is set when the die temperature exceeds the warning threshold (<math>T_J &gt; T_{WRN}</math>). Once set, this bit is not cleared until the register is read. The current status of the thermal shutdown condition can be read in the Status register.</p> <p>0: The die temperature has not exceeded the overtemperature warning threshold.</p>

**STATUS Register [A2, A1, A0] = [000]**

Bit	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Bit Name	ThShut	DiLvl	DoFault	CQFault	V24W	UV24	CQLvl	TempW
Read/Write	R	R	R	R	R	R	R	R
POR State	0	0	0	0	0	0	0	0
Reset Upon Read	N	N	N	N	N	N	N	N

The Status register reflects current state of various IC functions.

BIT	NAME	DESCRIPTION
7	ThShut	<b>Thermal Shutdown Status</b> 1: This bit is set when the MAX14827 has entered thermal shutdown mode. 0: This bit is cleared automatically when the device exits thermal shutdown.
6	DiLvl	<b>DI Logic Level</b> 1: This bit is set when the DI voltage is a logic high ( $V_{DI} < V_{TL}$ ). 0: This bit is clear when the DI voltage is a logic low ( $V_{DI} > V_{TH}$ ).
5	DoFault	<b>DO Driver Fault Status</b> 1: This bit is set when a fault occurs on the DO driver (over current or over heating). 0: This bit is cleared automatically when the fault on DO is removed.
4	CQ_Fault	<b>C/Q Driver Fault Status</b> 1: This bit is set when a fault occurs on the C/Q driver (over current or over heating). 0: This bit is cleared automatically when the fault on C/Q is removed.
3	V24W	<b>V24 Low Voltage Warning Status</b> 1: This bit is set when V24 falls below the IO-Link low-voltage warning threshold ( $V_{24} < V_{24W}$ ). 0: This bit is cleared automatically when V24 rises above the low-voltage warning threshold.
2	UV24	<b>V24 Supply Status</b> 1: This bit is set when V24 falls below the UVLO threshold ( $V_{24} < V_{24UVLO}$ ). 0: This bit is cleared automatically when V24 rises above the UVLO threshold.
1	CQLvl	<b>C/Q Logic Level</b> 1: This bit is set when the C/Q voltage is a logic high ( $V_{C/Q} < V_{TL}$ ). 0: This bit is clear when the C/Q voltage is a logic low ( $V_{C/Q} > V_{TH}$ ).
0	TempW	<b>Overtemperature Warning</b> 1: This bit is set when the die temperature exceeds the warning threshold ( $T_J > T_{WRN}$ ). 0: This bit is cleared automatically when the when the die temperature falls below the warning threshold and hysteresis ( $T_J < T_{WRN} - T_{WRN\_HYST}$ ).

**MODE Register [A2, A1, A0] = [010]**

Bit	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Bit Name	RST	WU_Dis	V33_Dis	ENMPX	V24WEn	CQFil	LED2b	LED1b
Read/Write	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
POR State	0	0	0	0	0	0	0	0
Reset upon Read	N	N	N	N	N	N	N	N

Use the Mode register to configure the MAX14827 and manage the 3.3V LDO.

BIT	NAME	DESCRIPTION
		<b>Register Reset</b>
7	RST	1: Reset all registers to their default power-up state. The Status register is cleared and $\overline{\text{IRQ}}$ deasserts (if asserted) when RST = 1. Interrupts are not generated while RST = 1. 0: Normal operation.
		<b>Wake-Up Interrupt Disable/Enable</b>
6	WU_Dis	1: Wake-up detection is disabled. 0: Enable IO-Link wake-up detection.
		<b>V33 Enable/Disable</b>
5	V33_Dis	1: Disable the V33 linear regulator. 0: Enable the V33 linear regulator.
		<b>Enable/Disable SPI/UART Multiplexing</b>
4	ENMPX	1: Enable UART multiplexing on SPI interface pins. See the Mode Selection Table for more information. 0: Disable UART multiplexing on SPI interface pins.
		<b>V24 Undervoltage Warning Enable</b>
3	V24WEn	1: Enable the V24 undervoltage warning interrupt. V24WInt is set when V24 falls below the UVLO threshold. 0: Disable the V24 undervoltage warning interrupt.
		<b>C/Q Deglitch Filter Enable/Disable</b>
2	CQFil	1: Deglitch filter is disabled on RX. 0: Deglitch filter is enabled on RX.
		<b>LED2 Driver Logic</b>
1	LED2b	1: Set the LED2 output high. 0: Set the LED2 output low.
		<b>LED1 Driver Logic.</b>
0	LED1b	1: Set the LED1 output high. 0: LED1 output is driven by the LED1IN logic input.

**CURRLIM Register [A2, A1, A0] = [011]**

Bit	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Bit Name	CL1	CL0	CL_Dis	CL_BL1	CL_BL0	TAr1	TAr0	ArEN
Read/Write	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
POR State	0	0	0	0	0	0	0	0
Reset Upon Read	N	N	N	N	N	N	N	N

The CURRLIM register sets the C/Q and DO driver current limits and the fixed off-time once the drivers have exceeded their individual thermal shutdown thresholds.

BIT	NAME	DESCRIPTION
7	CL1	<b>Driver Current Limit</b> Set the CL1 and CL0 bits to select the active current limit for the C/Q and DO drivers when CL_Dis = 0.
6	CL0	00: Driver current limit is set to 50mA 01: Driver current limit is set to 100mA 10: Driver current limit is set to 200mA 11: Driver current limit is set to 250mA
5	CL_Dis	<b>Driver Current Limit Disable/Enable</b> 1: Disable the driver current limit for the C/Q and DO drivers. 0: Enable the driver current limit (as set by the CL1 and CL0 bits).
4	CL_BL1	<b>Current Limit Blanking Time</b> Set the CL_BL1 and CL_BL0 bits to select the minimum blanking time to signal a current limit or thermal fault.
3	CL_BL0	00: Blanking time is 128µs 01: Blanking time is 500µs 10: Blanking time is 1ms 11: Blanking time is 5ms
2	TAr1	<b>Auto-Retry Fixed Off-Time</b> Set the TAr1 and TAr0 bits to select the fixed driver off-time after a fault has been generated when auto-retry functionality is enabled (ArEn = 1). The driver is re-enabled automatically after the fixed off-delay.
1	TAr0	00: Fixed off-time is 50ms 01: Fixed off-time is 100ms 10: Fixed off-time is 200ms 11: Fixed off-time is 500ms
0	ArEN	<b>Auto-Retry Fixed Off-Time Enable/Disable</b> 1: Fixed off-time functionality is enabled. C/Q and DO drivers are disabled for a fixed time after an overcurrent or thermal fault occurs. The driver is re-enabled automatically after the fixed off-delay. 0: Fixed off-time functionality is disabled. The driver is re-enabled after temperature falls below the thermal hysteresis.

**CQConfig Register [A2, A1, A0] = [100]**

Bit	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
<b>Bit Name</b>	RX_Dis	CQ_WPD	C/Q_WPU	C/QDOPar	C/Q_NPN	CQ_PP	CQ_Q	CQ_Dis
<b>Read/Write</b>	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
<b>POR State</b>	0	0	0	0	0	0	0	1
<b>Reset Upon Read</b>	N	N	N	N	N	N	N	N

Use the CQConfig register to control the C/Q driver and receiver parameters. All bits in the CQConfig register are read-write.

BIT	NAME	DESCRIPTION
7	RX_Dis	<b>Receiver Disable/Enable</b> 1: The RX receiver output is disabled. RX is high impedance when disabled. 0: RX is enabled.
6	CQ_WPD	<b>C/Q Weak Pull-Down Enable</b> 1: Enable the weak pull-down current sink on the C/Q driver. 0: Disable the weak pull-down current sink on the C/Q driver.
5	CQ_WPU	<b>C/Q Weak Pull-Up Enable</b> 1: Enable the weak pull-up current source on the C/Q driver. 0: Disable the weak pull-up current source on the C/Q driver.
4	CQDOPar	<b>C/Q and DO Driver Tracking</b> 1: Enable C/Q and DO tracking. In this mode, both C/Q and DO switch as a function of the TX input or the CQ_Q bit. 0: C/Q and DO operate independently.
3	CQ_NPN	<b>C/Q Driver NPN/PNP Mode</b> 1: Enable NPN operation (when CQ_PP = 0) on the C/Q driver. 0: Enable PNP operation (when CQ_PP = 0) on the C/Q driver. CQ_NPN is ignored when CQ_PP = 1.
2	CQ_PP	<b>C/Q Driver Push-Pull Mode</b> 1: Enable push-pull operation on the C/Q driver. 0: Enable open-drain (PNP or NPN mode) operation on the C/Q driver.
1	CQ_Q	<b>C/Q Driver Output Logic</b> 1: Set the C/Q driver high (push-pull mode), set the C/Q PNP switch on (PNP mode), or set the C/Q NPN switch off (NPN mode). See Table 1. 0: CQ is high impedance when CQ_Q = 0 and TXEN is low (or CQ_Dis = 1). CQ logic is the inverse of TX logic when TXEN is high (and CQ_Dis = 0) and CQ_Q = 0. See Table 1.
0	CQ_Dis	<b>C/Q Driver Disable/Enable</b> 1: Disable the C/Q driver, regardless of the state of the TXEN input. The driver is high impedance in this mode. 0: Status of the C/Q driver is determined by the TXEN input or CQ_Q bit.

## DIOConfig Register [A2, A1, A0] = [101]

Bit	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Bit Name	-	DO_WPD	DO_WPU	DO_AV	DO_NPN	DO_PP	DO_Q	DO_Dis
Read/Write	R	R/W	R/W	R/W	R/W	R/W	R/W	R/W
POR State	0	0	0	0	0	0	0	1
Reset Upon Read	N	N	N	N	N	N	N	N

Use the DIOConfig register to control the DI and DO interfaces. All bits in the DIOConfig register are read-write.

BIT	NAME	DESCRIPTION
7	-	This bit is not used.
6	DO_WPD	<p><b>DO Weak Pull-Down Enable</b></p> <p>1: Enable the weak pull-down current sink on the DO driver. 0: Disable the weak pull-down current sink on the DO driver.</p>
5	DO_WPU	<p><b>DO Weak Pull-Up Enable</b></p> <p>1: Enable the weak pull-up current source on the DO driver. 0: Disable the weak pull-up current source on the DO driver.</p>
4	DO_AV	<p><b>DO Antivalent Operation</b></p> <p>1: Enable antivalent operation on the C/Q and DO outputs. In this mode, DO switches as a function of the LO input or the DO_Q bit, but with opposite logic. If CQDOPar = 1, both C/Q and DO switch as a function of TX and/or CQ_Q, but with opposite logic. 0: C/Q and DO switch with normal polarity.</p>
3	DO_NPN	<p><b>DO Driver NPN/PNP Mode</b></p> <p>1: Enable NPN operation (when DO_PP = 0) on the DO driver. 0: Enable PNP operation (when DO_PP = 0) on the DO driver. DO_NPN is ignored when DO_PP = 1.</p>
2	DO_PP	<p><b>DO Driver Push-Pull Mode</b></p> <p>1: Enable push-pull operation on the DO driver. 0: Enable open-drain (PNP or NPN mode) operation on the DO driver.</p>
1	DO_Q	<p><b>DO Driver Output Logic</b></p> <p>1: Set the DO driver high (push-pull mode), set the DO PNP switch on (PNP mode), or set the DO NPN switch off (NPN mode). See Table 1. 0: DO logic is the inverse of LO logic when DO_Dis = 0 and DO_Q = 0. See Table 1.</p>
0	DO_Dis	<p><b>DO Driver Disable/Enable</b></p> <p>1: Disable the DO driver. DO is high impedance when disabled. 0: State of the DO driver is determined by the LO input or the DO_Q bit.</p>

**SPI Interface**

The device communicates through an SPI-compatible 4-wire serial interface. The MAX14827 supports burst read/write access. The maximum SPI clock rate for the device is 12MHz. The SPI interface complies with clock

polarity CPOL = 0 and clock phase CPHA = 0 (see [Figure 7](#) and [Figure 8](#)).

The SPI interface is not available when V<sub>5</sub> or V<sub>L</sub> are not present.

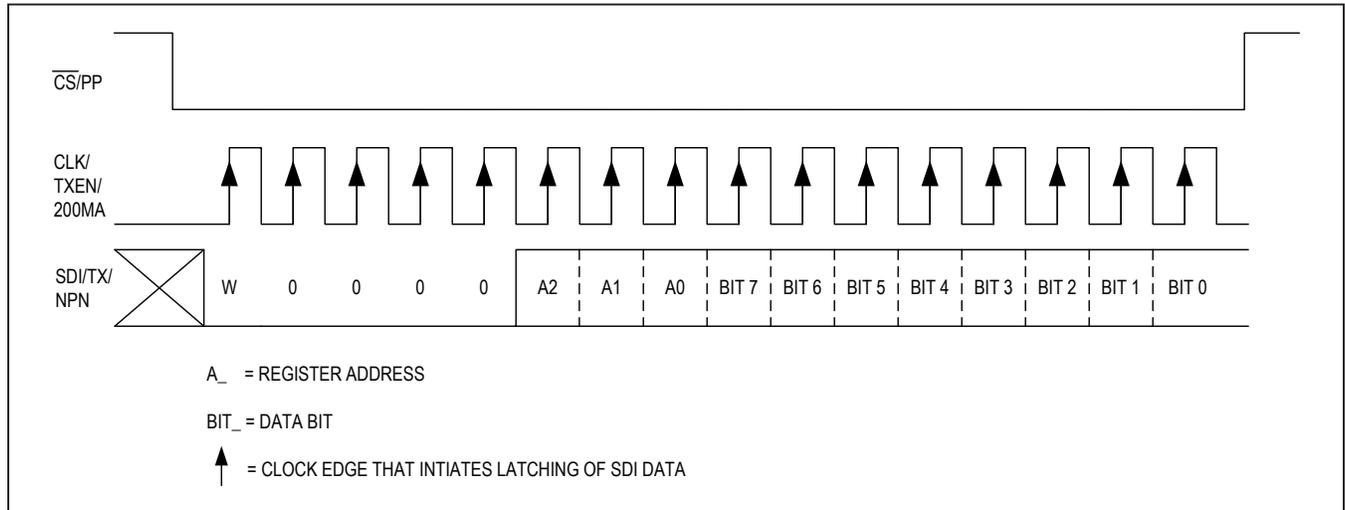


Figure 7. SPI Write Cycle

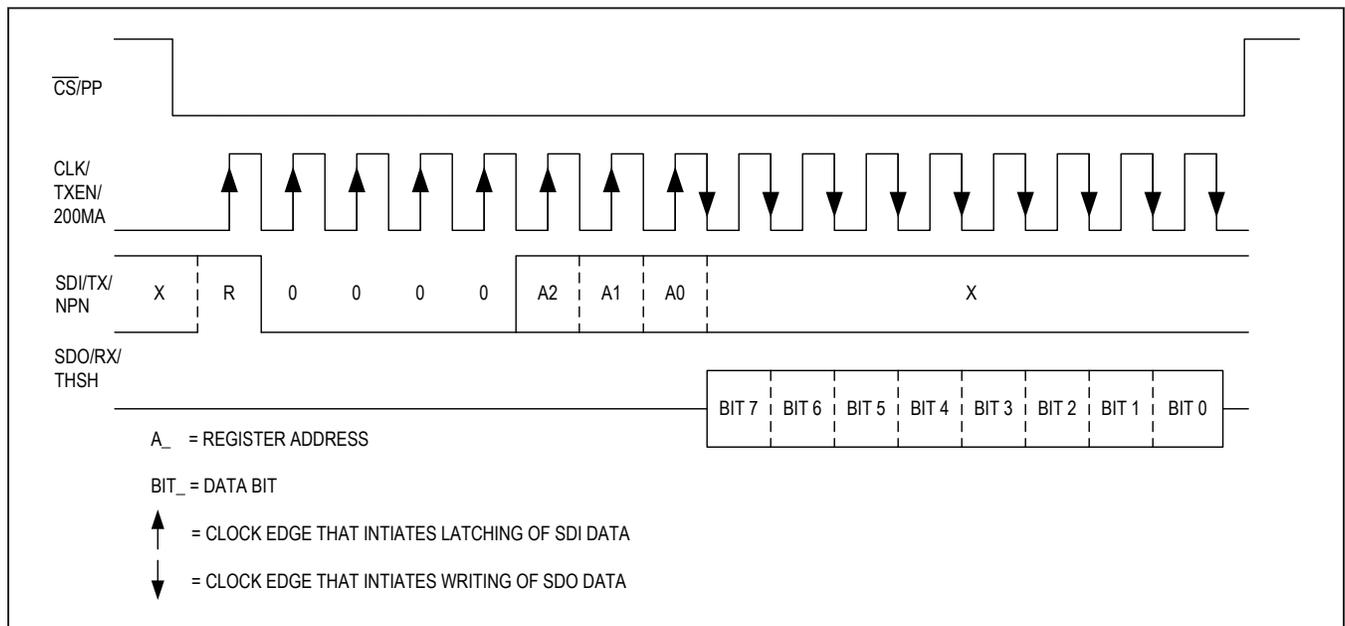


Figure 8. SPI Read Cycle



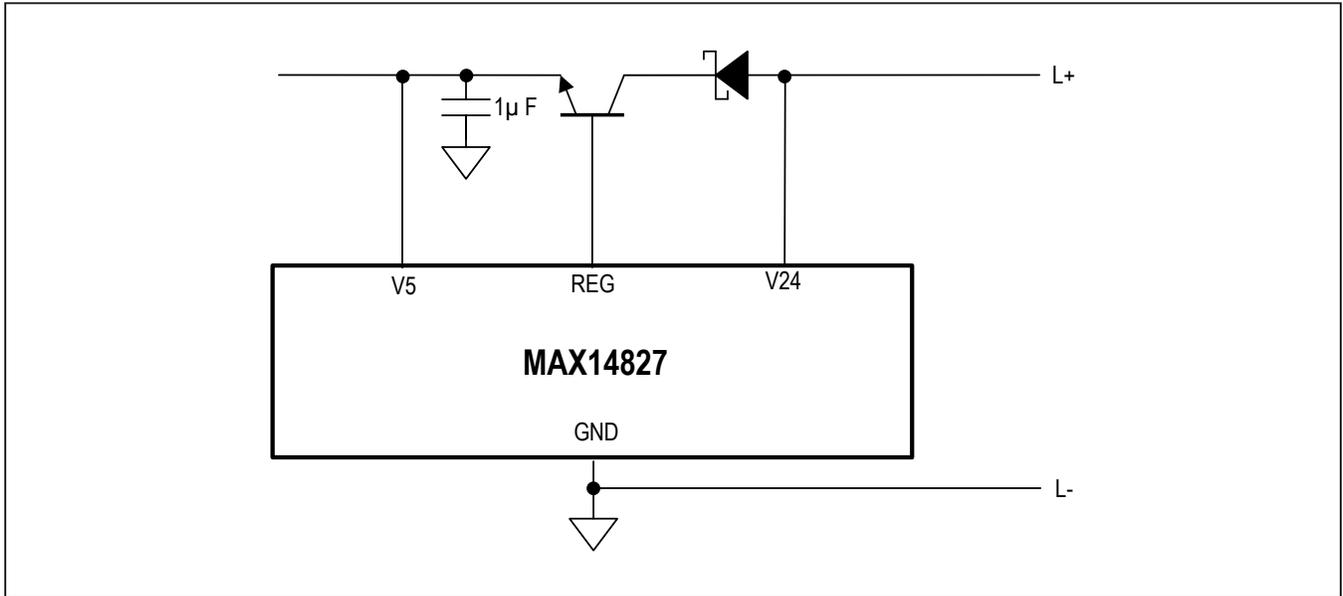


Figure 10. Using an External NPN Transistor with the 5V Regulator

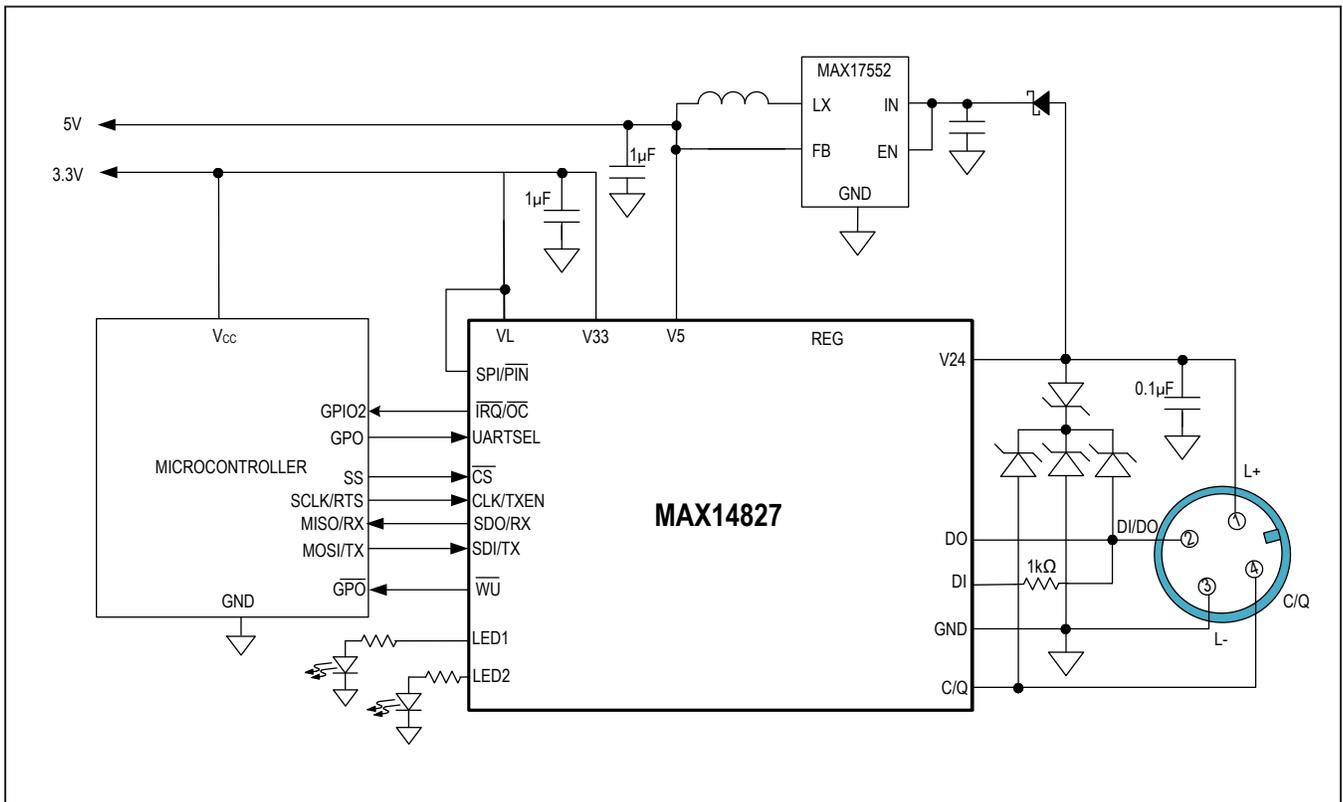


Figure 11. Using an External Step-Down with the 5V Regulator

**Shared SPI/UART Interface**

Figure 12 is an example of the use of a minimum pin-count microcontroller. A microcontroller serial port, which supports both UART and SPI functions, is used for managing both transceiver control (SPI) and IO-Link data communication (UART). The microcontroller's

shared UART and SPI interface pins are multiplexed. The transceiver's SPI is typically only used for configuration at power-up and occasionally afterwards for reconfiguration, and diagnostics. During an IO-Link master-device communication cycle, the idle time on the C/Q interface can be used for SPI activity. This is possible by slightly increasing the IO-Link device' minimum cycle time.

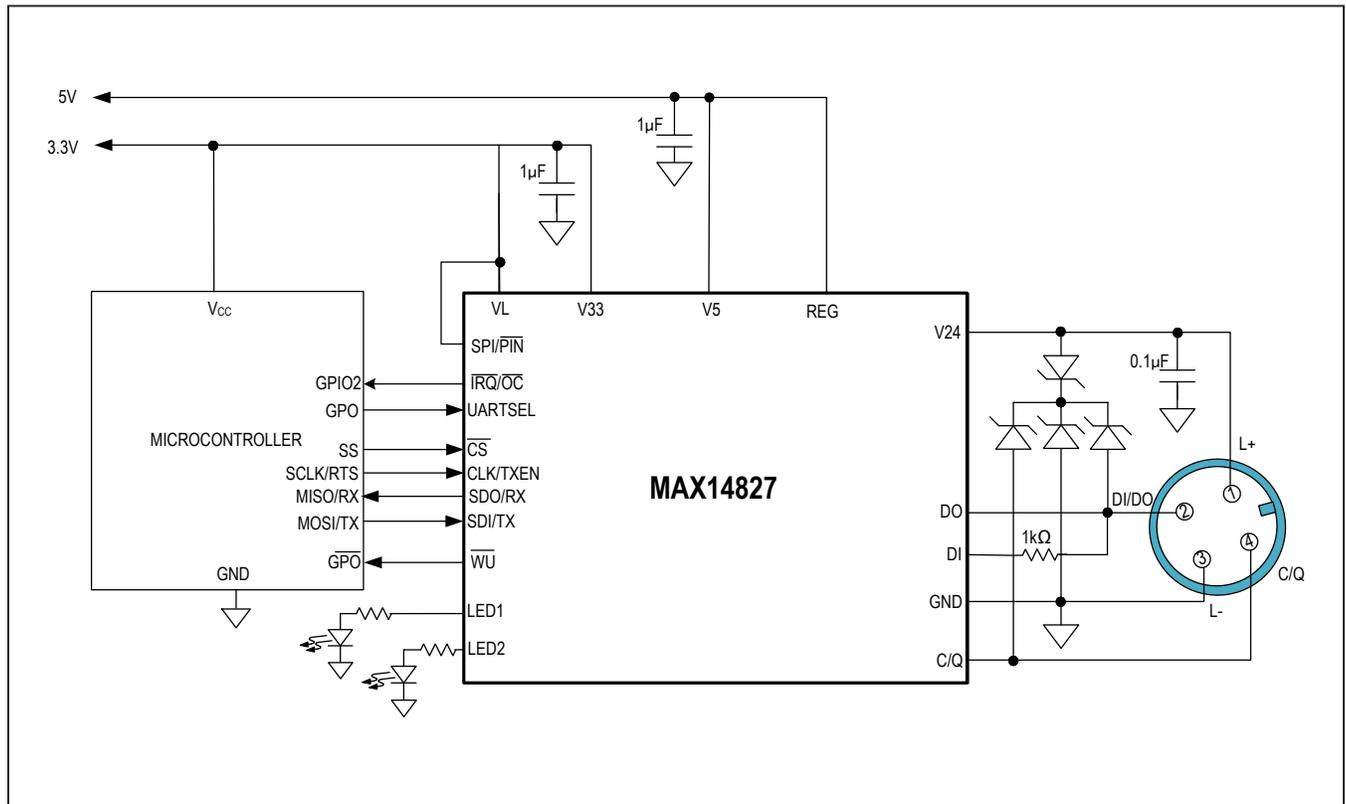


Figure 12. Multiplexed SPI/UART Mode Configuration

## Ordering Information

PART	TEMP RANGE	PIN-PACKAGE
<b>MAX14827ATG+</b>	-40°C to +125°C	24 TQFN-EP*
MAX14827ATG+T	-40°C to +125°C	24 TQFN-EP*
<b>MAX14827AWA+</b>	-40°C to +125°C	25 WLP
MAX14827AWA+T	-40°C to +125°C	25 WLP

+Denotes a lead(Pb)-free/RoHS-compliant package.

\*EP = Exposed pad.

T = Tape & Reel.

## Chip Information

PROCESS: BiCMOS

## Revision History

REVISION NUMBER	REVISION DATE	DESCRIPTION	PAGES CHANGED
0	12/15	Initial release	—
1	2/19	Updated the <i>Typical Operating Circuit</i> , <i>Pin Description</i> , <i>Wake-Up Detection</i> section, Figure 11, and Figure 12	1, 19, 25 38–39

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